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There are four Parts, assigned 1 point each, for a total of 4 points.

#### Part I (1 point):

A feedback system is shown in Figure 1 where P(s) is a system model and  $e^{-\tau s}$  represents transmission delay in the feedback path. The system transfer function can be fairly accurately



Figure 1: Feedback system.

modeled over the range of frequencies that are relevant to stability analysis by

$$P(s) = \frac{2}{\sqrt{s}}$$

for  $s = j\omega$  with  $\omega$  measured in radians/sec. It is also given that when the transmission delay  $\tau$  is sufficiently small or zero, the feedback system is bounded-input/bounded-output stable. Determine the maximal amount of time delay that the feedback system can tolerate before it becomes unstable.

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# Part II (1 point):

Determine the maximal interval  $[0, K_{\text{maximal}})$  for the gain K for which the delay-differential equation

$$\dot{y}(t) = u(t) - Ky(t) - 2Ky(t-1) - Ky(t-2)$$

is stable. Here, u(t) is thought of as the input to the system and y(t) as the output.

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## Part III (1 point):

Consider the feedback system in Figure 2. Do the following:



Figure 2: Feedback system.

i) Determine whether, for  $P(s) = \frac{s}{1-s}$ , the feedback loop is stable or not. ii) Determine whether, for  $P(s) = \frac{s}{(1-s)(1+\epsilon s)}$  and sufficiently small  $\epsilon$ , the feedback loop is stable or not.

iii) Determine whether, for  $P(s) = \frac{se^{-\tau s}}{1-s}$  and sufficiently small  $\tau$ , the feedback loop is stable or not.

iv) What conlcusions do you reach regarding the theoretical answer to part i)?

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## Part IV (1 point):

Consider the Nyquist plot computed for a transfer function G(s) and shown in Figure 3. Determine whether G(s) is stable or not, and explain your reasoning.

[Warning: the above question is <u>not</u> about the stability of the feedback system with G(s) in the forward path and, perhaps, negative unity feedback. The question is about whether G(s) itself is stable or not.]



Figure 3: Nyquist plots

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Space for your work: