

The meaning of Distances in Spectral Analysis

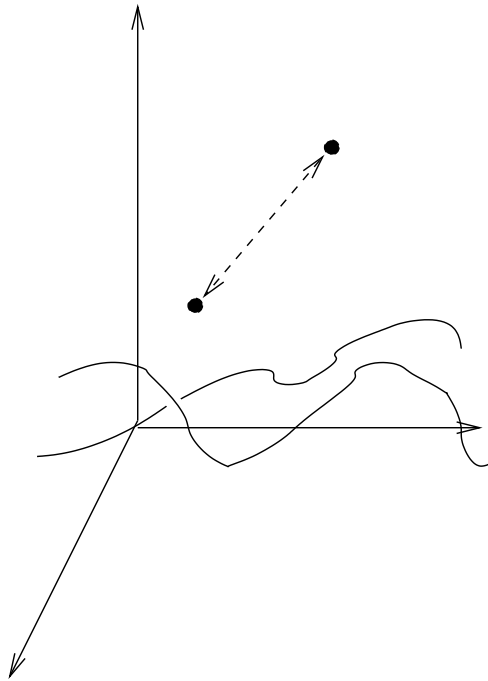
46th IEEE Conference on Decision & Control
Plenary presentation

Tryphon Georgiou

Electrical & Computer Engineering
University of Minnesota



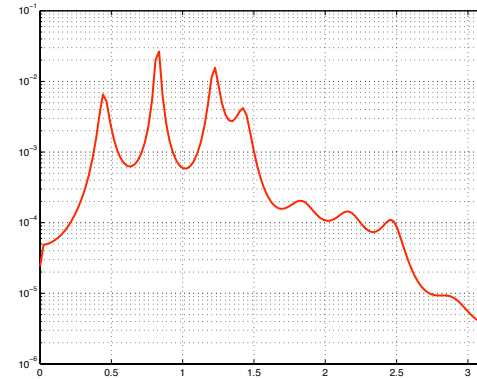
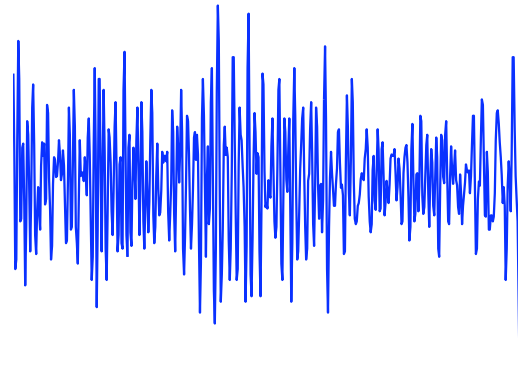
Meaning of distances



- maximal separation (L_∞)
- energy-like content (L_2)
- integral of flow-rate (L_1)



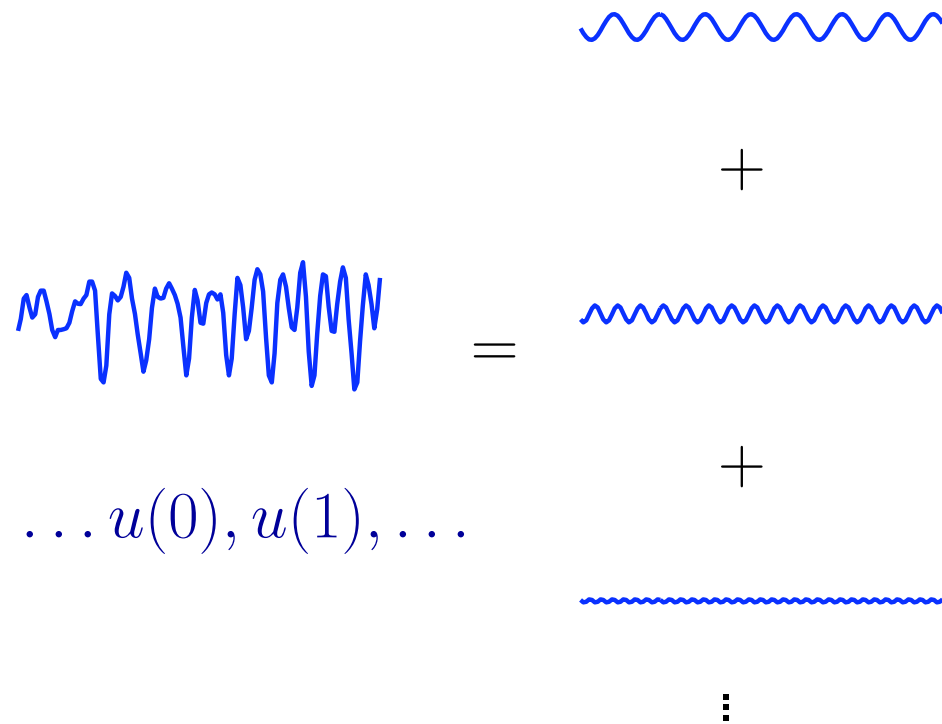
Power spectra



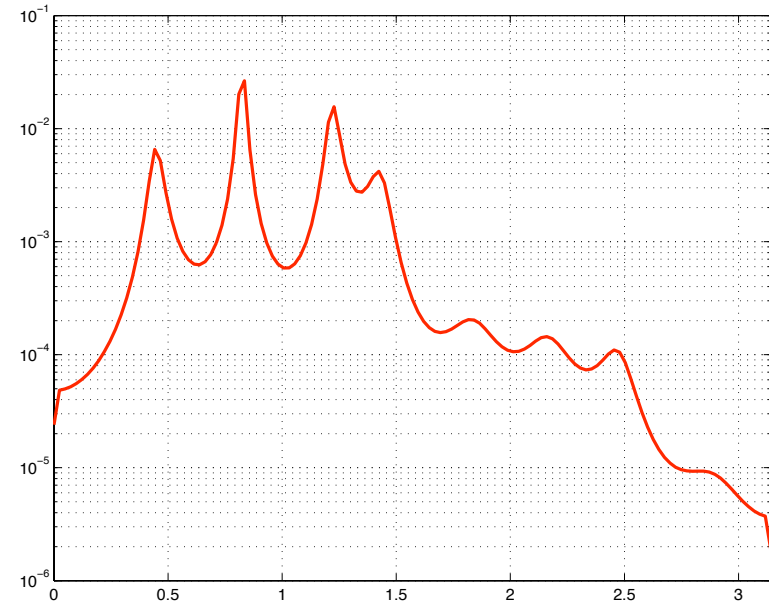
Periodogram, Blackman-Tukey, Levinson, Durbin, Burg, . . .



Spectral analysis



$$u(k) = \int e^{jk\theta} dX(\theta)$$

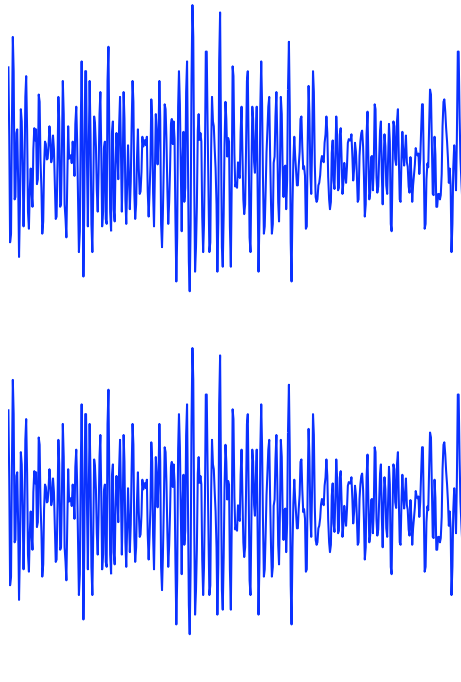


$$E\{u(k)u(k + \ell)\} = \int e^{j\ell\theta} f(\theta) d\theta$$



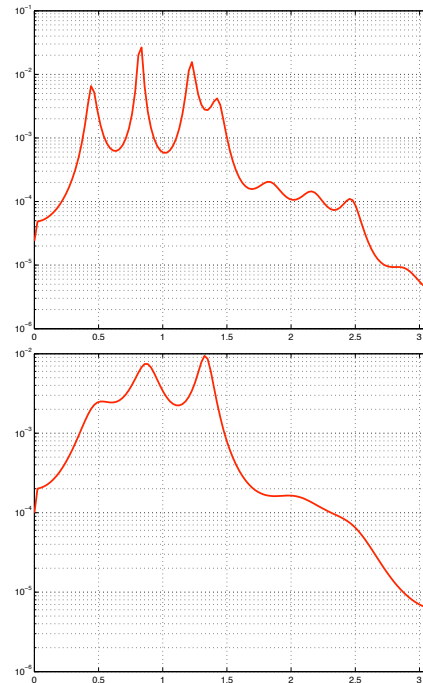
Signals vs. power densities

time-signals



$(u_1 - u_2)$ “error signal”

power distributions

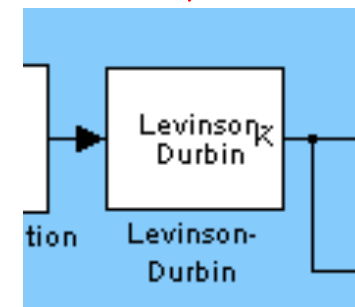
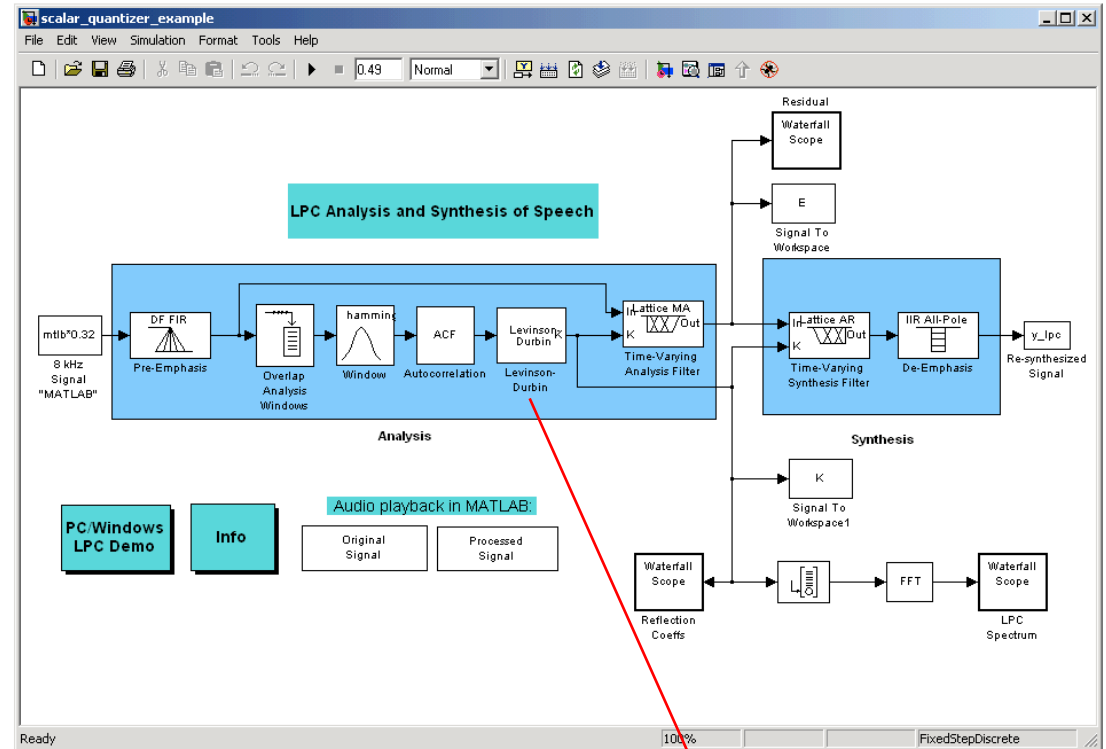
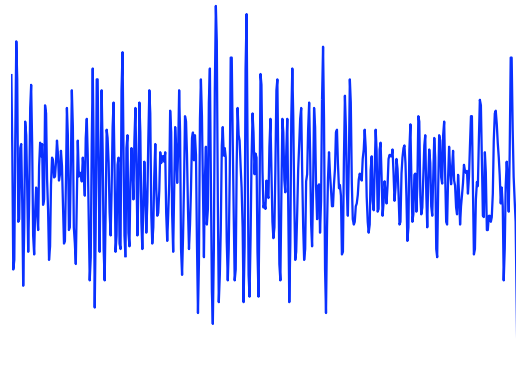


$(f_1 - f_2)$ is not a “signal”



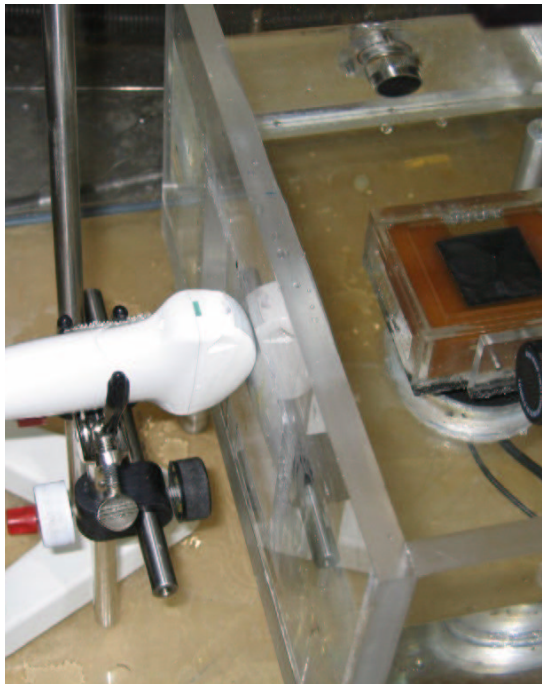
Communications

Speech analysis/coding

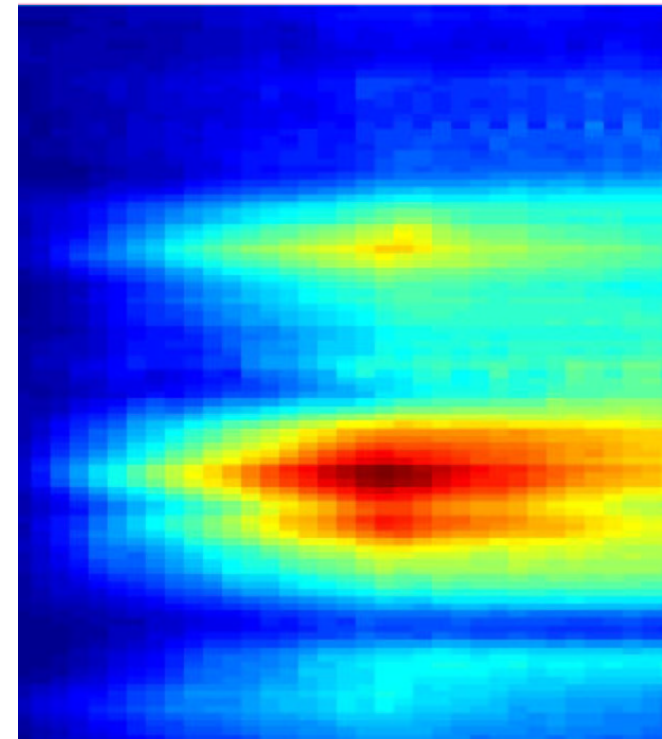




Medical diagnostics



Noninvasive temperature sensing



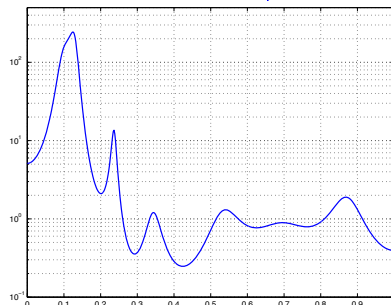
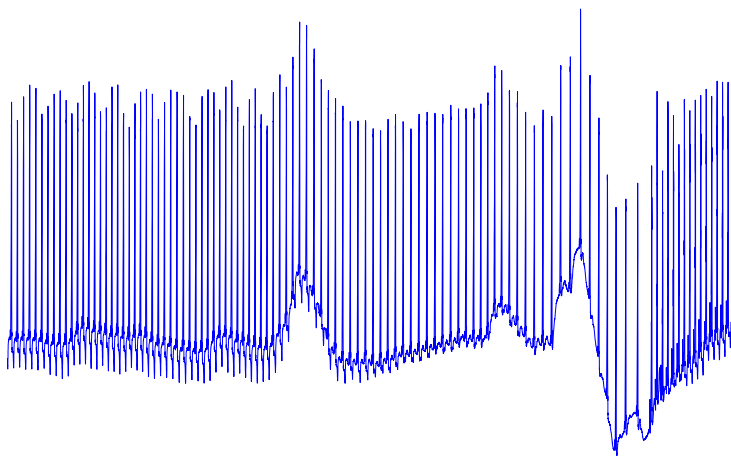
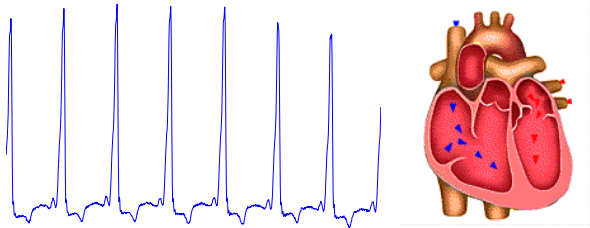
Temperature field

with E. Ebbini & A.N. Amini

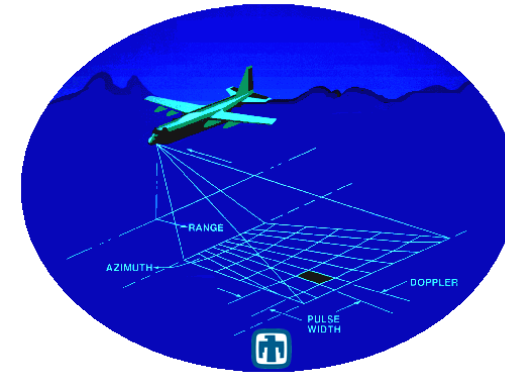
In IEEE Trans. on Biomedical Engineering, 2005



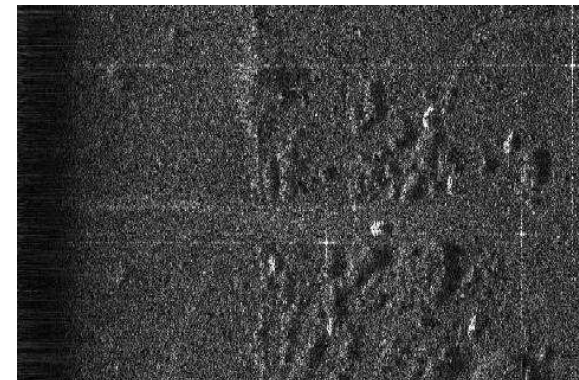
Medical diagnostics



Radar (SAR)

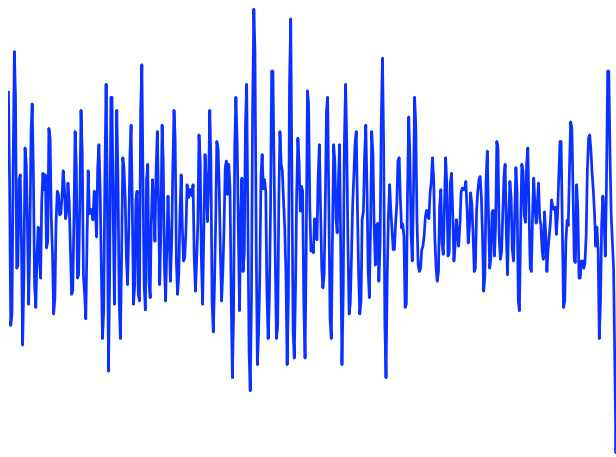


<http://www.sandia.gov/radar/images/3dsar.gif>

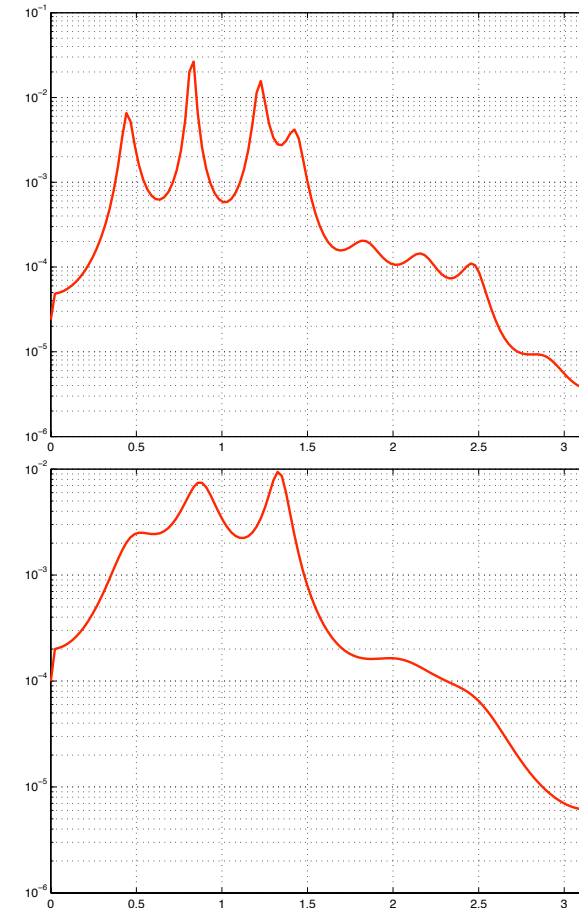




Quantitative analysis



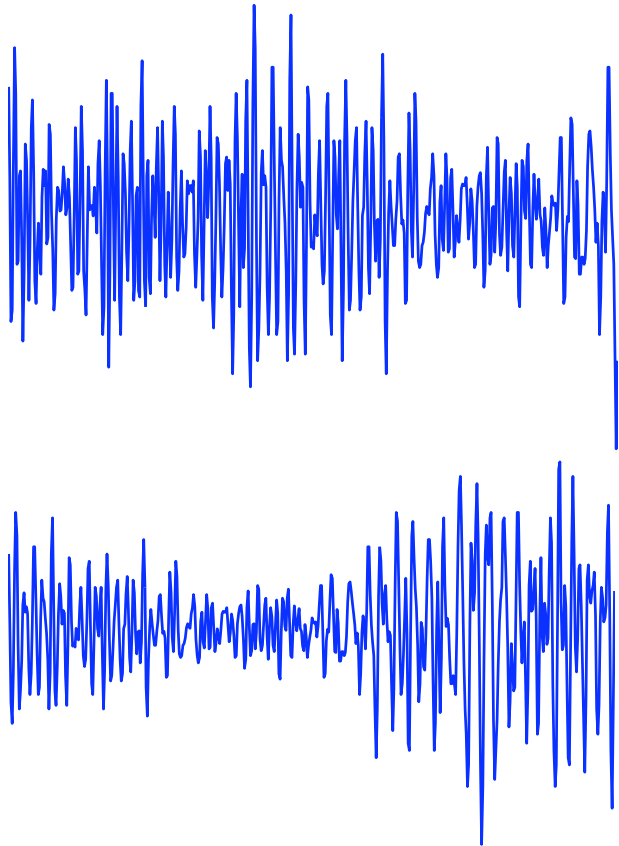
different
methods



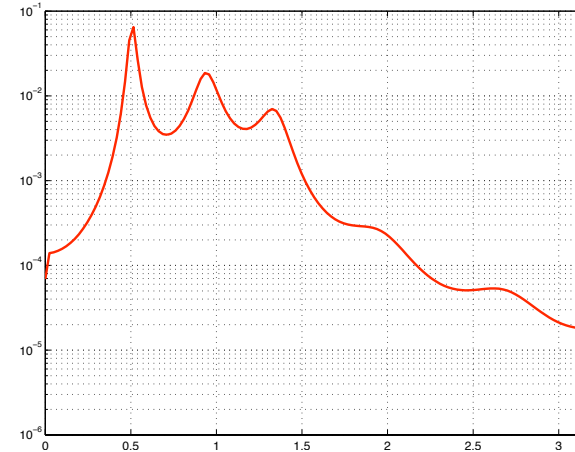
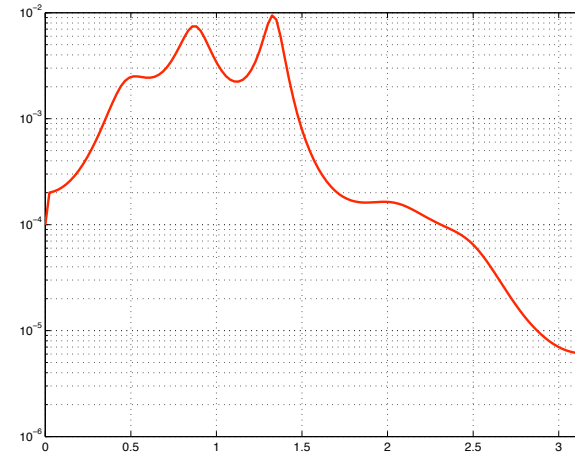
How can we compare power spectra?



Quantitative analysis



same
method



How can we compare power spectra?



How can we compare power spectra?

Question:

what is a natural notion of distance
between power spectral densities?



Plan of the talk

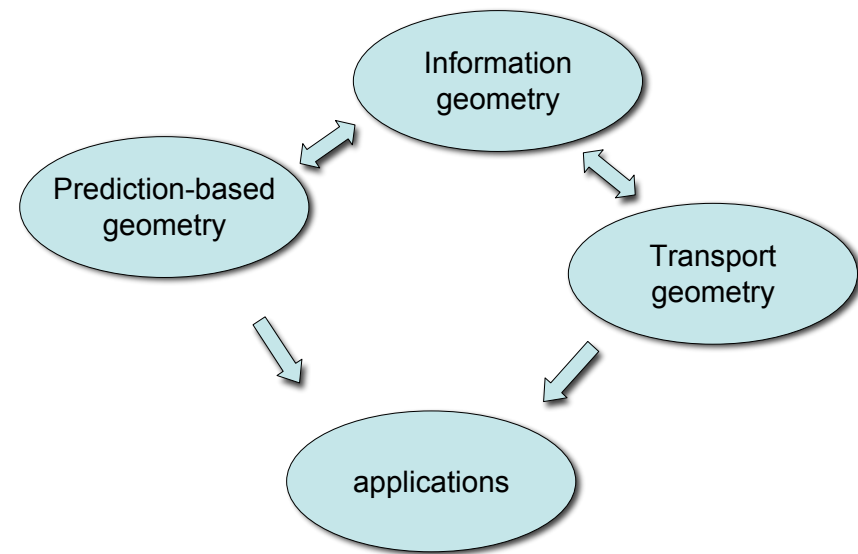
Metrics based on

prediction theory

some parallels with information geometry

transport geometry

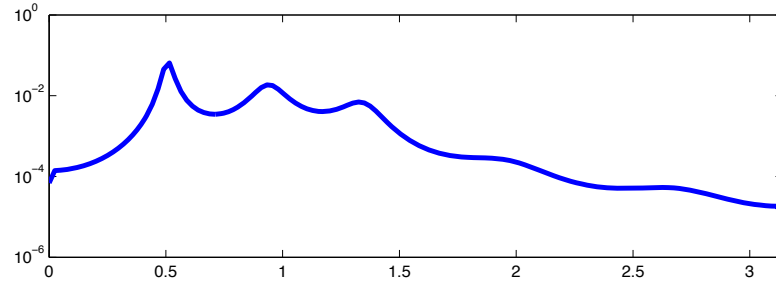
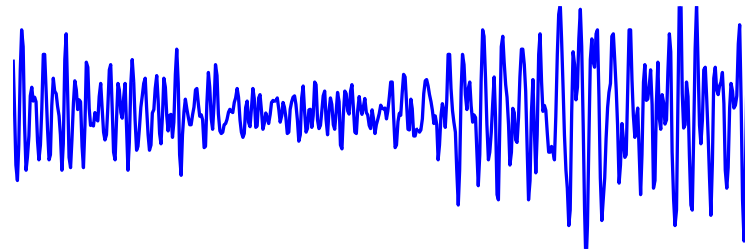
Case studies & applications





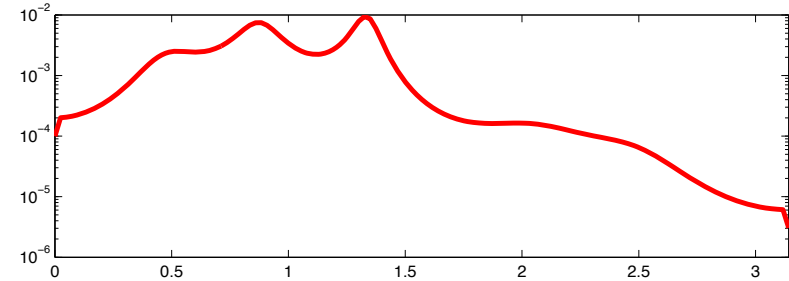
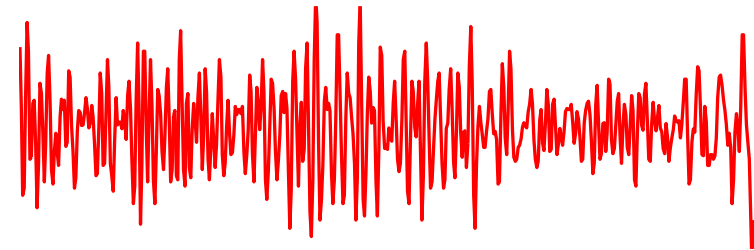
Setting

$\dots u_{-1}, u_0, u_1, u_2, \dots$



$f_1(\theta)$

$\dots u_{-1}, u_0, u_1, u_2, \dots$



$f_2(\theta)$



What is it we would like to have?

$$\text{distance} \left(\begin{array}{c} \text{[Plot of } f_1(\theta) \text{]} \\ f_1(\theta), \end{array} \begin{array}{c} \text{[Plot of } f_2(\theta) \text{]} \\ f_2(\theta) \end{array} \right)$$

- metric
- meaningful & natural

candidates?

[Kullback-Leibler](#), Bregman, Itakura-Saito, Makhoul,..

convex functionals
perceptual qualities



Linear prediction

One-step-ahead prediction: $u_{\text{present}} - \hat{u}_{\text{present}|\text{past}}$

with $\hat{u}_{\text{present}|\text{past}} := \sum_{\text{past}} \alpha_k u_k$

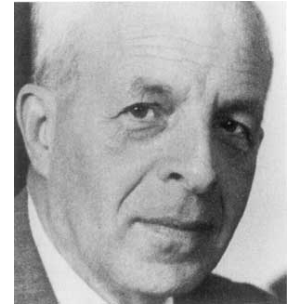
$$E\{|u_{\text{present}} - \hat{u}_{\text{present}|\text{past}}|^2\} = \text{variance of prediction error}$$



Szegő's theorem

One-step-ahead prediction:

$$\text{least error variance} = \exp \left\{ \frac{1}{2\pi} \int \log f(\theta) d\theta \right\}$$



G. Szegő

it is a geometric mean...

$$\exp \left\{ \frac{1}{3} (\log f_1 + \log f_2 + \log f_3) \right\} = \sqrt[3]{f_1 f_2 f_3}$$



Degradation of prediction error variance

Use f_2 to design a predictor (assuming $u_{f_2, \text{time}}$).

Then compare how this performs on $u_{f_1, \text{time}}$ against the optimal based on f_1 .

$$\frac{\overbrace{E\left\{\left|u_{f_1, \text{present}} - \sum_{\text{past}} a_{f_2, \text{past}} u_{f_1, \text{past}}\right|^2\right\}}^{\text{degraded variance}} - \text{optimal variance}}{\text{optimal variance}} \geq 0$$



Degradation of prediction variance

$$\frac{\overbrace{E\left\{\left|u_{f_1,\text{present}} - \sum_{\text{past}} a_{f_2,\text{past}} u_{f_1,\text{past}}\right|^2\right\}}^{\text{degraded variance}}}{\text{optimal variance}} = \frac{\text{arithmetic mean of } \left(\frac{f_1}{f_2}\right)}{\text{geometric mean of } \left(\frac{f_1}{f_2}\right)}$$
$$= \frac{\left(\frac{1}{2\pi} \int \left(\frac{f_1}{f_2}\right) d\theta\right)}{\exp\left(\frac{1}{2\pi} \int \log\left(\frac{f_1}{f_2}\right) d\theta\right)}$$

arithmetic over *geometric* mean (≥ 1)



Riemannian metric

$$f_1 = f,$$

$$f_2 = f + \Delta$$

$$\frac{\overbrace{E\left\{\left|u_{f_1,\text{present}} - \sum_{\text{past}} a_{f_2,\text{past}} u_{f_1,\text{past}}\right|^2\right\}}^{\text{degraded variance}} - \text{optimal variance}}{\text{optimal variance}} \simeq$$

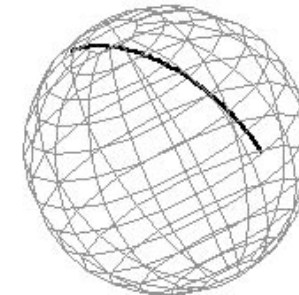
$$\delta(f, f + \Delta) = \frac{1}{2\pi} \int \left(\frac{\Delta}{f}\right)^2 d\theta - \left(\frac{1}{2\pi} \int \left(\frac{\Delta}{f}\right) d\theta\right)^2$$

variance-like: (mean square) - (arithmetic-mean)²



Geodesics

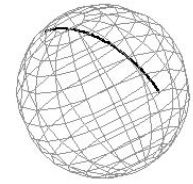
Paths $f_{\mathbf{r}}$ ($\mathbf{r} \in [0, 1]$) between f_0, f_1 of minimal length $\int_0^1 \sqrt{\delta(f_{\mathbf{r}}, f_{\mathbf{r}+d\mathbf{r}})}$



each point represents a different power spectral density

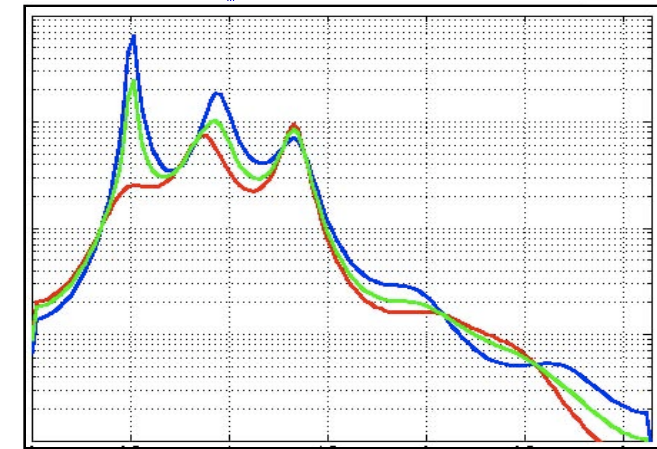
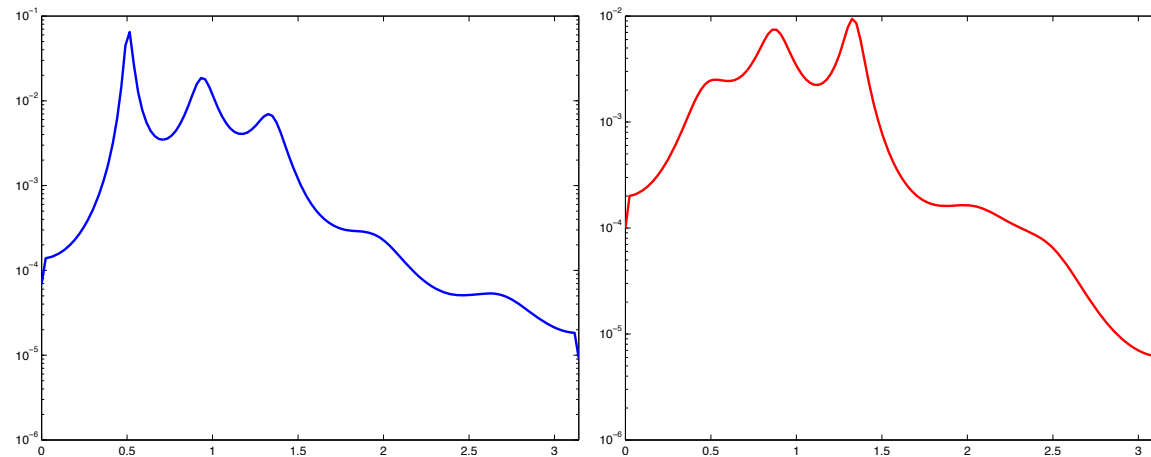
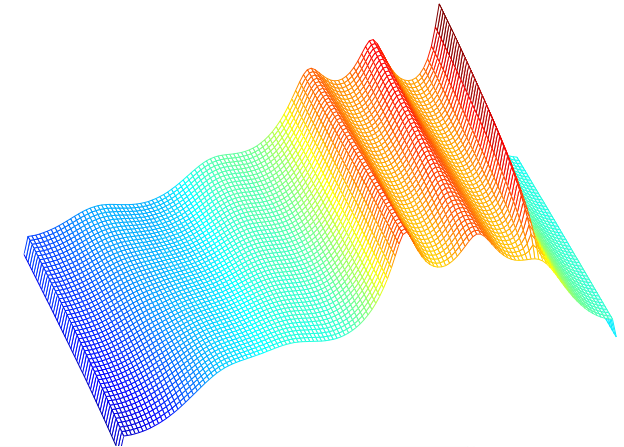


Geodesics



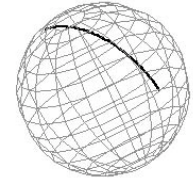
The geodesics are exponential families:

$$f_{\mathbf{r}} = f_0 \left(\frac{f_1}{f_0} \right)^{\mathbf{r}}, \quad \mathbf{r} \in [0, 1]$$
$$= \exp \{ (1 - \mathbf{r}) \log (f_0) + \mathbf{r} \log (f_1) \}$$





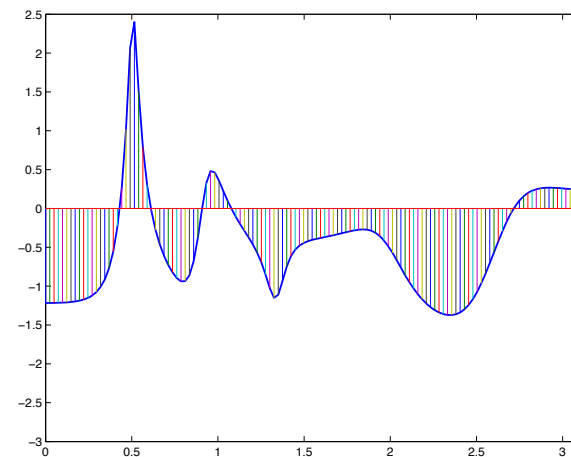
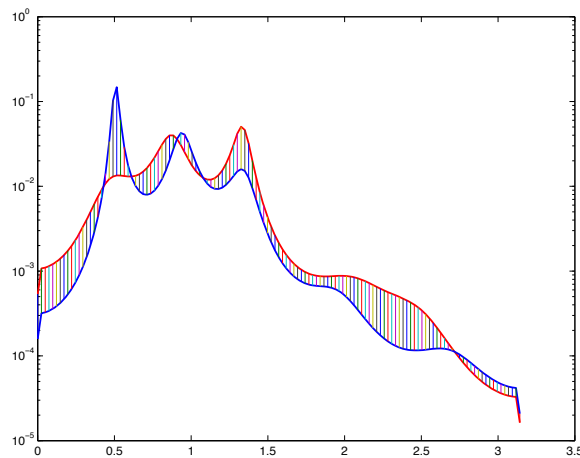
Geodesic distance: metric



The path-length is

$$d(f_0, f_1) := \sqrt{\frac{1}{2\pi} \int_{-\pi}^{\pi} \left(\log \frac{f_1}{f_0} \right)^2 d\theta - \left(\frac{1}{2\pi} \int_{-\pi}^{\pi} \log \left(\frac{f_1}{f_0} \right) d\theta \right)^2}$$

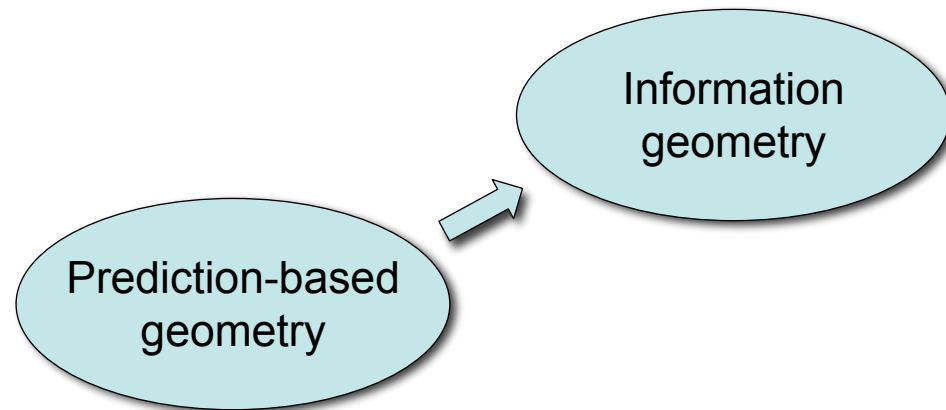
variance-like distance on logarithms: (mean square) - (arithmetic-mean)²
scale-insensitive, “shape” recognizer



$$\log \frac{f_1}{f_0} = \log(f_1) - \log(f_0)$$

In IEEE Trans. on Signal Processing, Aug. 2007

New Orleans, December 2007





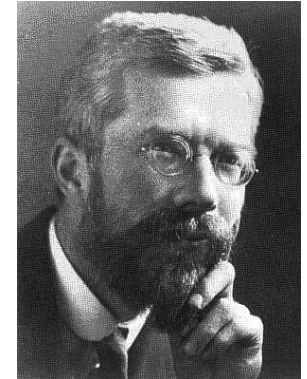
Information geometry – *parallels*

$f \rightsquigarrow \mathbf{p}$: probability density

$$I = E_{\mathbf{p}}\{(\partial_{\lambda} \log \mathbf{p}_{\lambda})^2\} \delta\lambda^2$$

Fisher information metric

$$I = \sum \frac{\Delta^2}{\mathbf{p}}$$



R. Fisher



C.R. Rao



Information geometry – *parallels*



R. Leibler

Expected “message-length increase”:

$$H(\mathbf{p}_1|\mathbf{p}_0) = \left(-\sum \mathbf{p}_1 \log(\mathbf{p}_0)\right) - \left(-\sum \mathbf{p}_1 \log(\mathbf{p}_1)\right)$$



S. Kullback

Fisher information metric

$$\mathbf{p}_0 = \mathbf{p}$$

$$\mathbf{p}_1 = \mathbf{p} + \Delta$$

$$I = \sum \frac{\Delta^2}{\mathbf{p}}$$



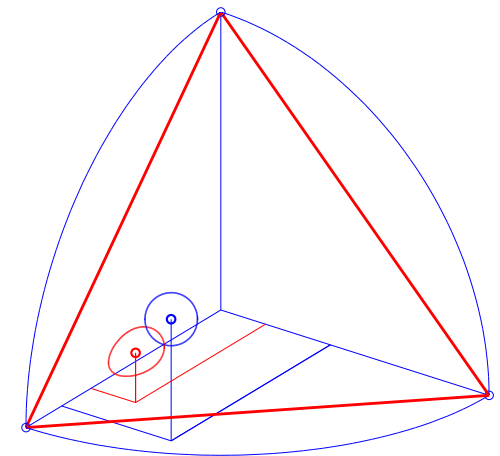
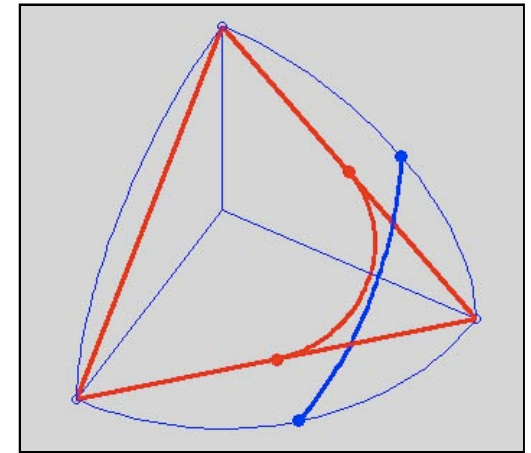
Information geometry – *parallels*

Geodesics: great circles

$$\mathbf{p} \mapsto \sqrt{\mathbf{p}} \in \text{Sphere}$$

$$\begin{pmatrix} p(1) \\ p(2) \\ p(3) \end{pmatrix} \mapsto \begin{pmatrix} \sqrt{p(1)} \\ \sqrt{p(2)} \\ \sqrt{p(3)} \end{pmatrix}$$

Geodesic distance: Arclength
Battacharyya distance





Information vs. prediction-based

$$\sum \frac{\Delta^2}{p}$$

vs.

$$\int \left(\frac{\Delta}{f} \right)^2 - \left(\int \frac{\Delta}{f} \right)^2$$

$$p \mapsto \sqrt{p}$$

vs.

$$f \mapsto \log f$$

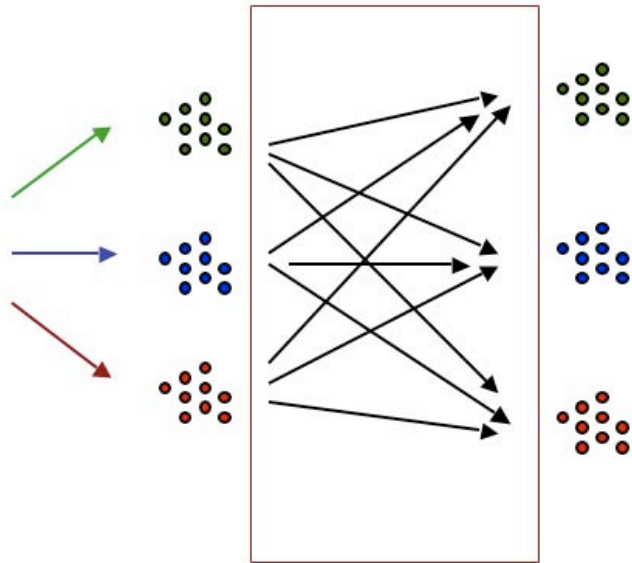
great circles

vs.

logarithmic families



Information geometry – *parallels*



Ability to differentiate decreases

$$\begin{pmatrix} p(1) \\ p(2) \\ p(3) \end{pmatrix} \mapsto M \begin{pmatrix} p(1) \\ p(2) \\ p(3) \end{pmatrix}$$

Chentsov's theorem:

Stochastic maps are contractive

under *Fisher metric*

and

Fisher metric is the unique Riemannian metric with this property



What is the analog for power spectra?

additive noise

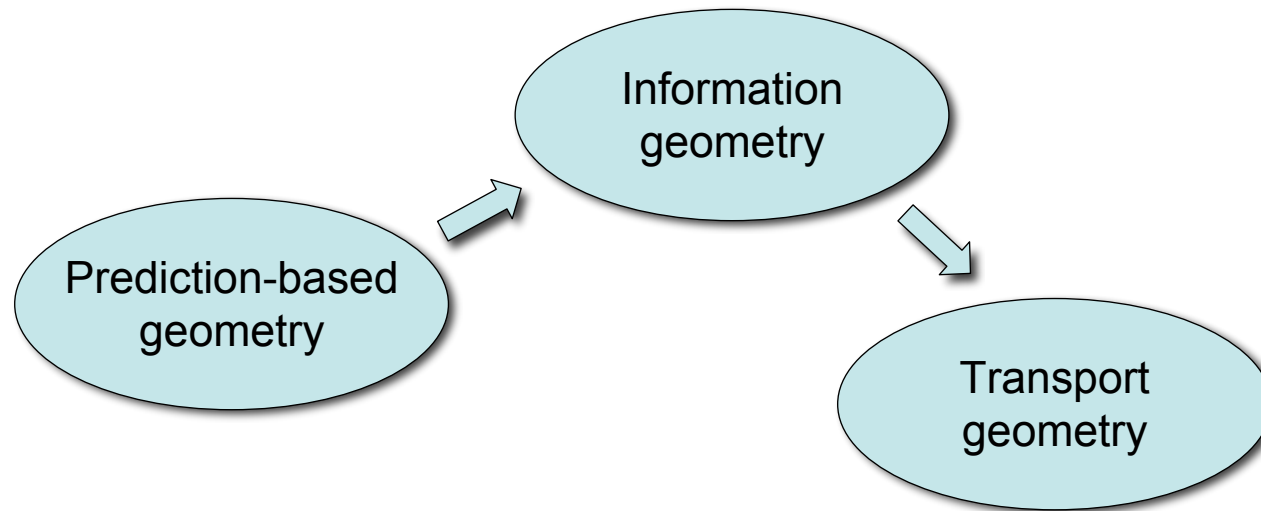
$$f \mapsto f + f_{\text{noise}}$$

multiplicative noise

$$f \mapsto f \star f_{\text{noise}}$$

continuity of moments (second-order statistics)

$$f \mapsto \text{integrals of } f$$



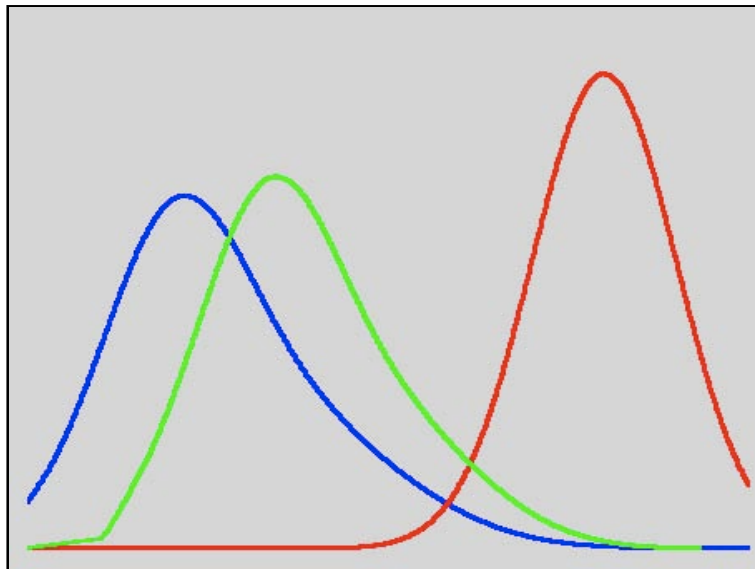


Transport geometry

Monge-Kantorovich problem

minimize cost of transferring mass

$$\int \text{cost}(x \rightarrow y) \times \text{mass}(dx, dy)$$



G. Monge, Comte de Péluse.

1748-1818

G. Monge



L. Kantorovich



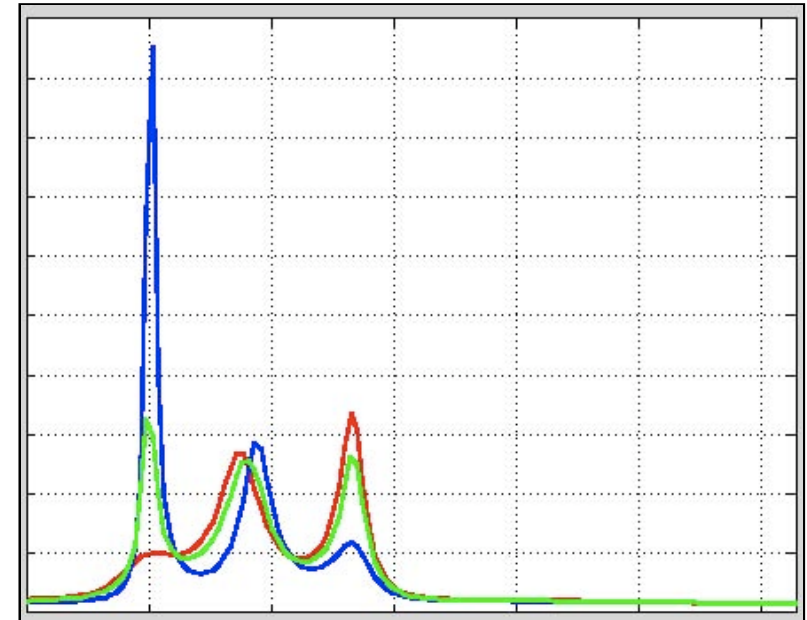
Transport for power spectra

Transport-based metric

distances do not increase

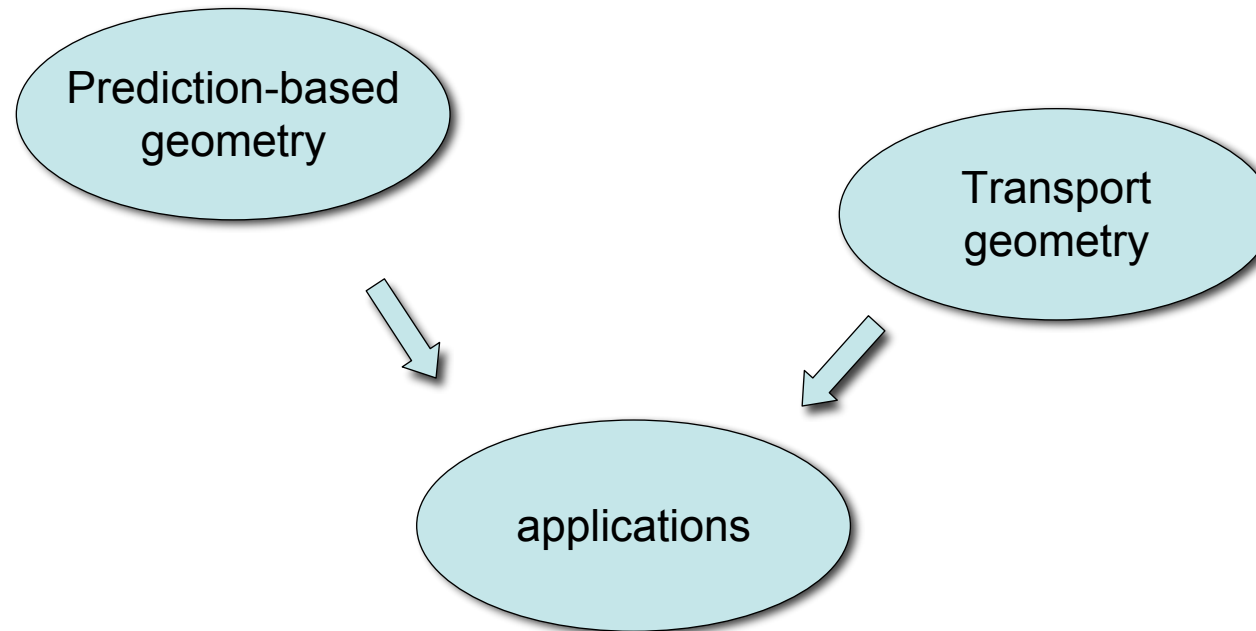
under additive noise
and multiplicative noise
with power ≤ 1

+ continuity of statistics



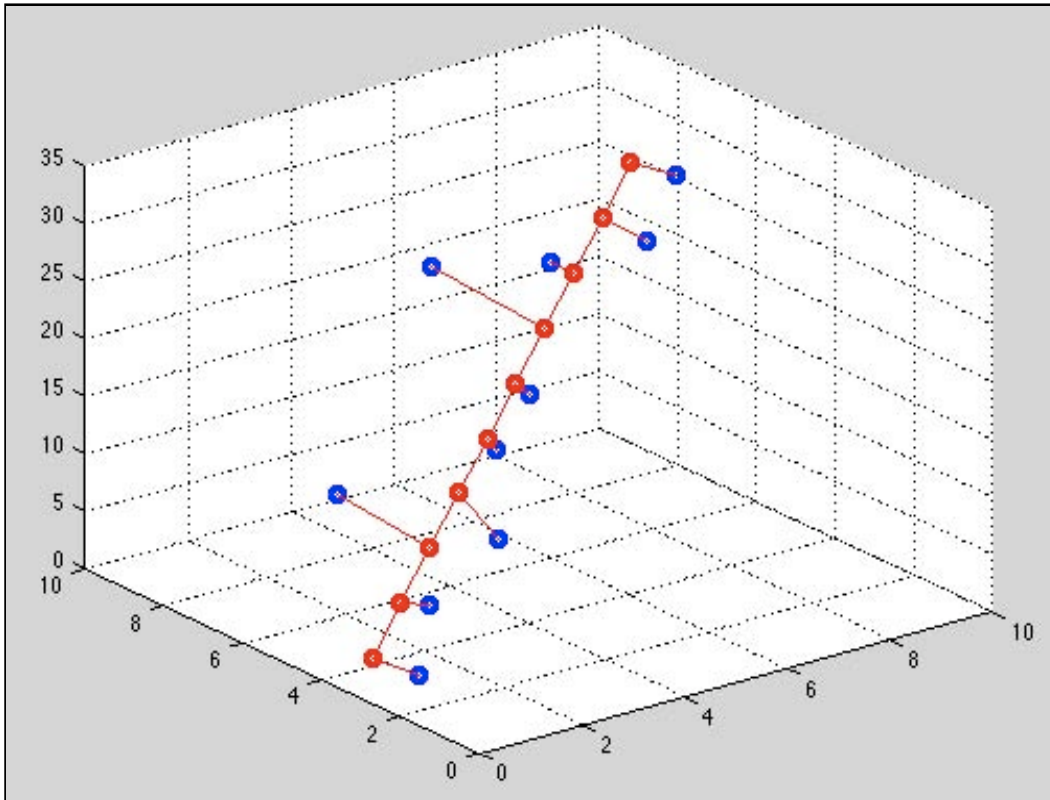
$$\mathbf{metric} = \min (\text{cost of transport}(\hat{f}_0, \hat{f}_1) + \text{normalization})$$

with Johan Karlsson (KTH) & Mir Shahrouz Takyar





Fitting geodesics

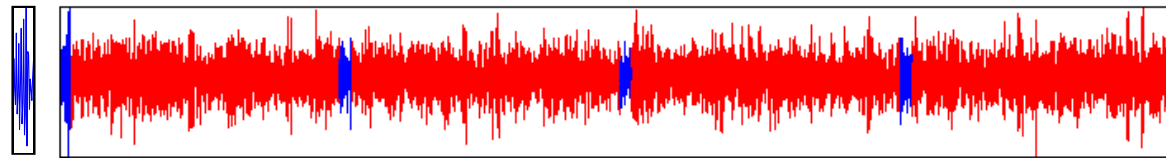


K.F. Gauss

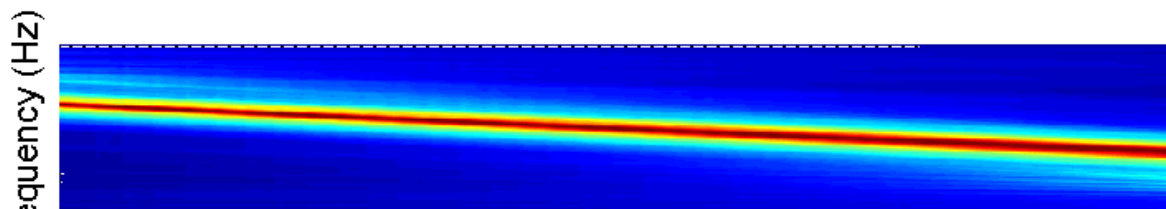
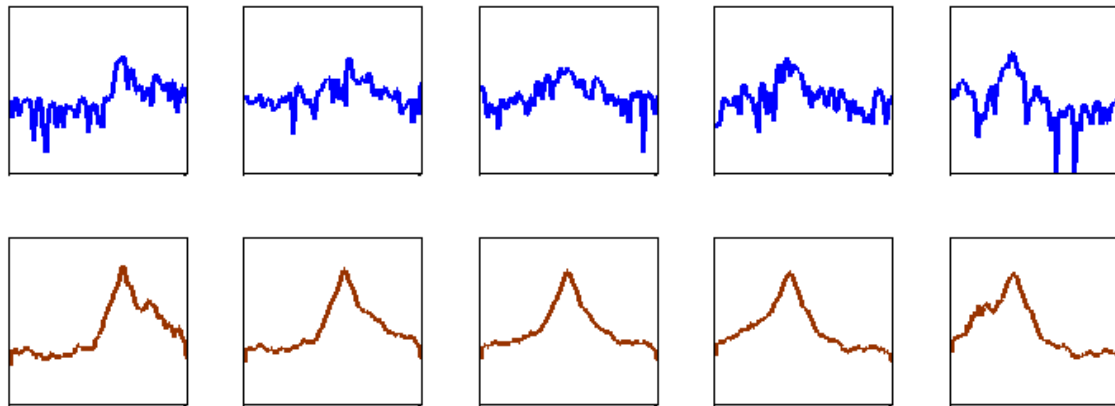
Least squares: The theory of motion of heavenly bodies, Gauss, K.F.



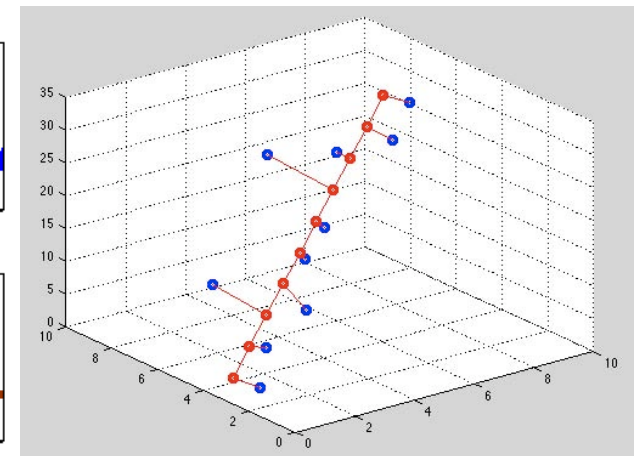
Tracking with geodesics



Time



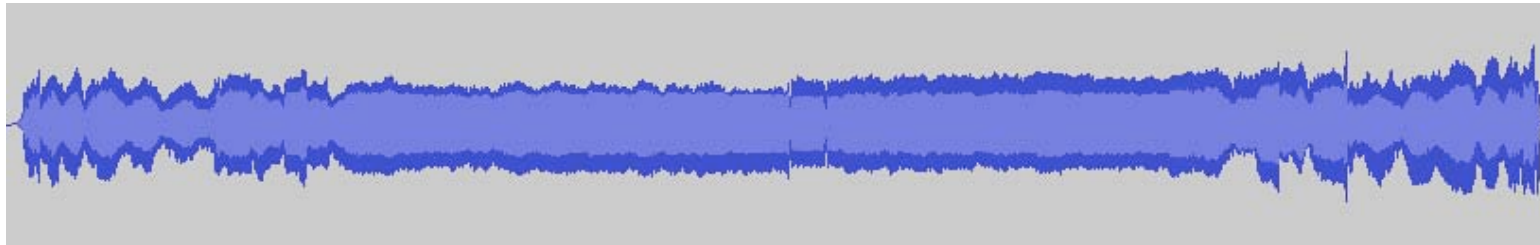
Time



with Xianhua Jiang



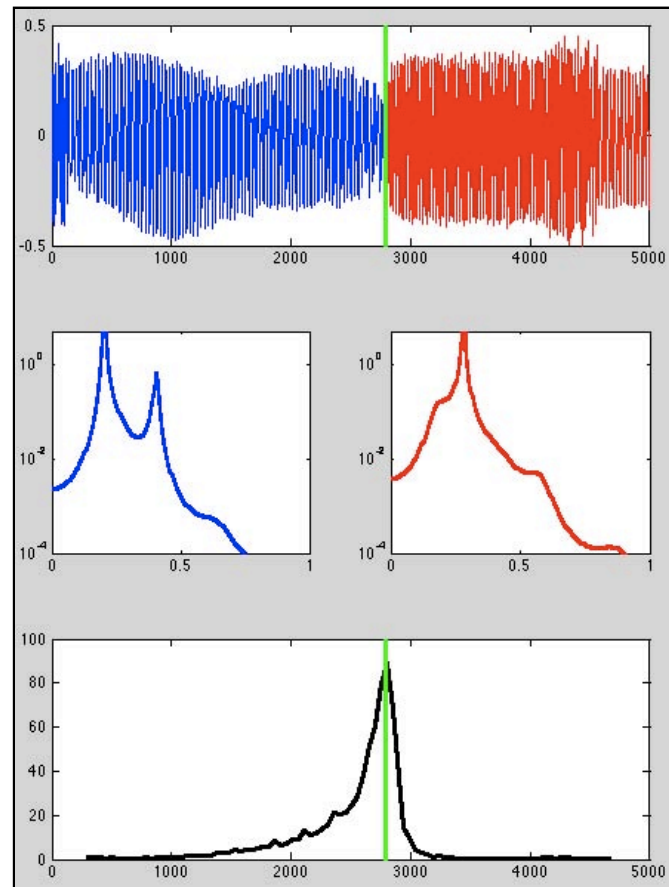
Voice & sounds



John Weissmuller's MGM Tarzan Yell



<http://www.complxmind.com>

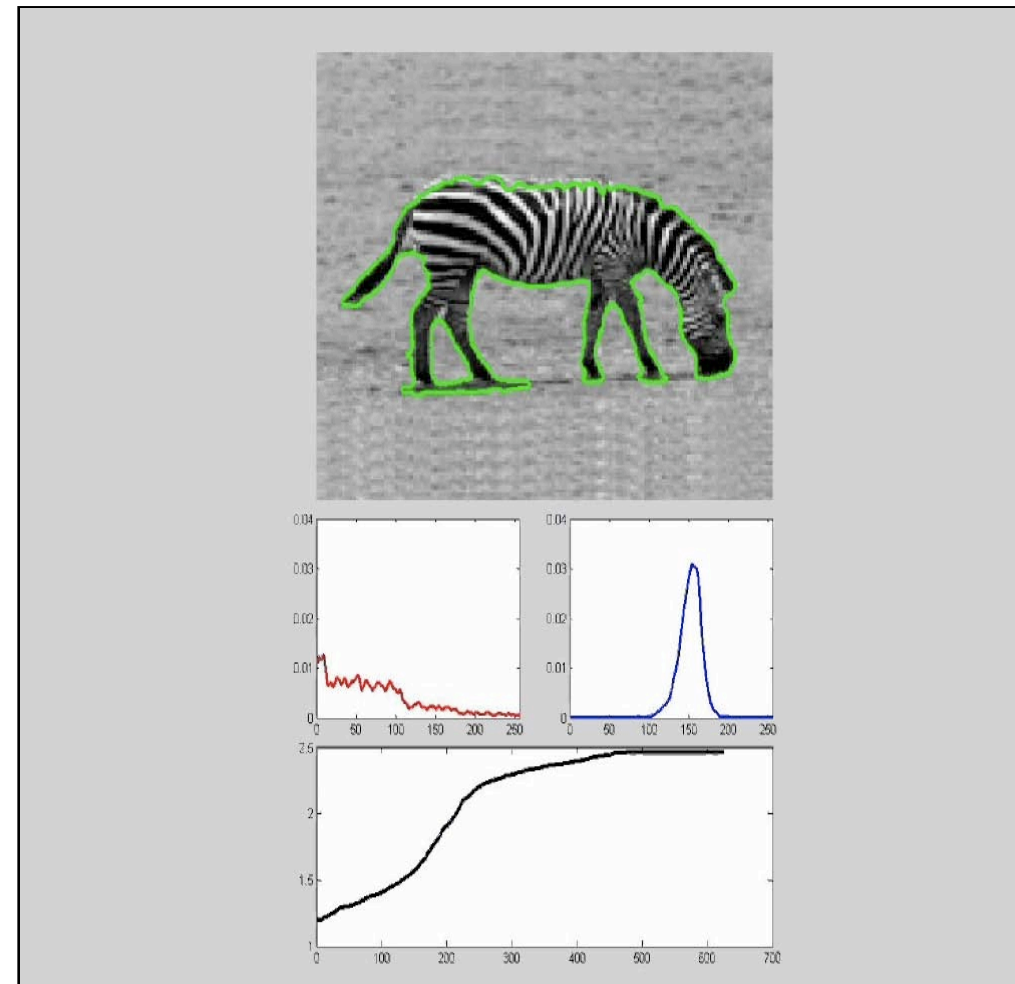
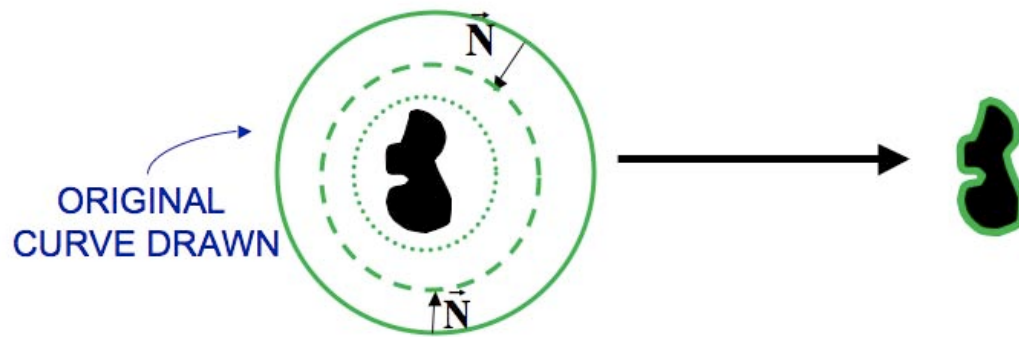




Images & more

Geometric active contours

$$\frac{\partial}{\partial t} \text{Curve} = \nabla_{\text{Curve}} \text{metric}(f_{\text{inside}}, f_{\text{outside}})$$



with Romeil Sandhu and Allen Tannenbaum



Images & more



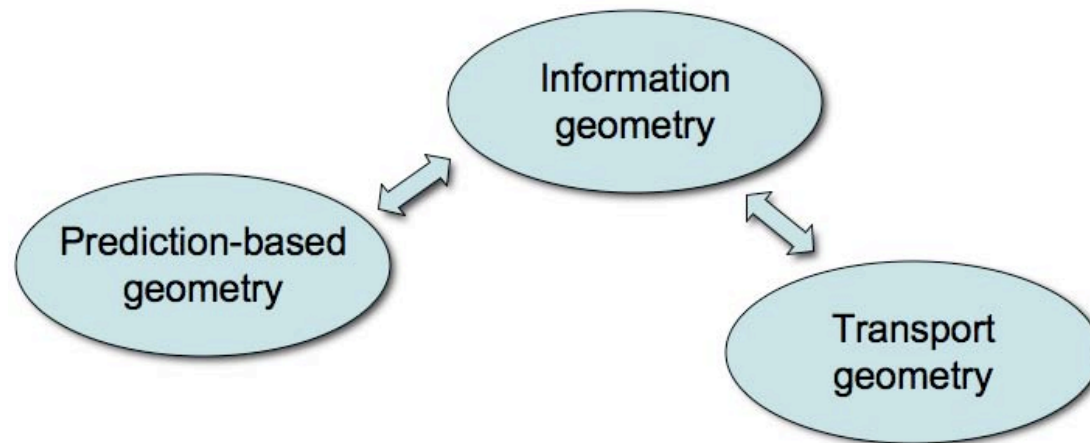
with Romeil Sandhu and Allen Tannenbaum



Concluding thoughts

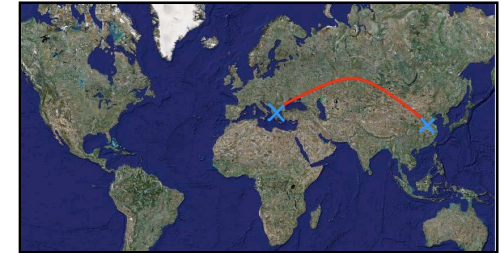
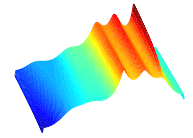
*Metrics
in spectral analysis*

- Operational significance
- Effect of natural transformations





Thank you for your attention



thanks to

Xianhua Jiang



Johan Karlsson



Romeil Sandhu



Mir Shahrouz Takyar



Allen Tannenbaum & Anders Lindquist

National Science Foundation, AFOSR, and Hermes-Luh endowment