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Due Monday 10/23/06

1. Give, if possible, an example of the following
  - (a) A continuous-time signal with bounded energy and unbounded magnitude.
  - (b) A continuous-time signal with bounded energy, unbounded action.
  - (c) A discrete-time signal with bounded energy and unbounded power.
  - (d) A discrete-time signal with bounded action and unbounded magnitude.
  - (e) A linear time-invariant discrete-time system that is BIBO stable and  $\ell_2$  unstable.
  - (f) A continuous-time linear time-invariant state space system that is asymptotically stable and BIBO unstable.
  - (g) A discrete-time linear time-invariant state space system that is asymptotically stable and BIBO unstable.
  - (h) A discrete-time linear time-invariant state space system where the origin is stable in the sense of Lyapunov and BIBO unstable.
2. Determine the  $H_\infty$ ,  $H_2$ , and  $L_1$  norms of the following systems:
  - (a)  $H(s) = \frac{1}{s+a}$ , with  $a > 0$ . How do these norms compare to each other for different values of  $a$ ? What happens for  $a = 0$ ?
  - (b) 
$$\begin{aligned} \dot{x}_1 &= x_2, \\ \dot{x}_2 &= -x_1 + u, \\ y &= x_1. \end{aligned}$$
3. Write a MATLAB program to compute the  $H_\infty$  norm of a SISO transfer function using the grid (in frequency) method. Test your program on the function

$$H(s) = \frac{1}{s^2 + 10^{-6}s + 1},$$

and compare your answer to the exact solution (computed by hand using the definition of the  $H_\infty$  norm).

4. Consider the system parameterized by  $k$  and  $R$

$$\begin{aligned} \begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} &= \begin{bmatrix} -(1+k^2)/R & 0 \\ k & -(2+k^2)/R \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 1 \\ 0 \end{bmatrix} u, \\ y &= x_2. \end{aligned}$$

- (a) For what values of  $k$  and  $R$  is this system stable?
- (b) Derive the formula for the  $H_2$  norm of this system as a function of  $k$  and  $R$ . Using this formula, plot the  $H_2$  norm as a function of  $k$  for  $R = 1$  and  $R = 1000$ , and as a function of  $R$  for  $k = 2$ .
- (c) Find the solution of the unforced system (i.e. determine operator  $G(t)$  that maps initial conditions to the output  $y(t)$ ,  $y(t) = G(t)x_0$ ).
- (d) Plot the maximal singular value of  $G(t)$  as a function of time (on time interval  $t \in (0, 1000)$ ) for two different cases: a)  $R = 1000$ ,  $k = 0$ ; b)  $R = 1000$ ,  $k = 2$ . How do these two cases compare to each other. Explain the obtained results.