Due Wednesday 10/15/08

1. Use the (matrix) exponential series to evaluate  $e^{At}$  for:

(a) 
$$A = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$$
,  
(b)  $A = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$ .

- 2. What kind of equilibrium stability (stable (in the sense of Lyapunov), or AS, or GAS) if any, is exhibited by the state representation of
  - (a) The  $\frac{1}{s^2}$  plant with no input, i.e.  $\dot{x}_1 = x_2$ ,  $\dot{x}_2 = 0$ .

(b) The magnetically suspended ball: 
$$\dot{x}_1 = x_2$$
  
 $\dot{x}_2 = -\frac{c}{m}\frac{\bar{u}^2}{x_1^2} + g$  with  $\bar{u} = \sqrt{\frac{mg}{c}Y} = \text{const.}$ 

3. The Morse oscillator is a model that is frequently used in chemistry to study reaction dynamics. The equations for an unforced Morse oscillator are given by

$$\dot{x}_1 = x_2,$$
  
 $\dot{x}_2 = -\mu(e^{-x_1} - e^{-2x_1}).$ 

- (a) Find the equilibrium points of the system.
- (b) Investigate their stability properties.
- 4. Consider the following nonlinear system

$$\dot{x}_1 = -\frac{x_2}{1+x_1^2} - 2x_1 \dot{x}_2 = \frac{x_1}{1+x_1^2}.$$

- (a) Show that the origin is an equilibrium point.
- (b) Using the candidate Lyapunov function

$$V(x) = x_1^2 + x_2^2,$$

what are the stability properties of the equilibrium point?

- (c) Linearize the nonlinear system around the equilibrium point.
- (d) What can you deduce about the stability properties of the origin using Lyapunov indirect method?
- (e) Obtain a suitable Lyapunov function by solving the Lyapunov equation

$$A^T P + P A = -Q,$$

where

$$Q = \left[ \begin{array}{cc} 2 & 0 \\ 0 & 2 \end{array} \right].$$

5. (a) Suppose A(t) is an  $n \times n$  time-varying matrix with continuous entries that satisfies

$$A(t)\left(\int_{t_0}^t A(\sigma)d\sigma\right) = \left(\int_{t_0}^t A(\sigma)d\sigma\right)A(t).$$

Show that the state transition matrix  $\Phi(t_1, t_0)$  can be computed as

$$\Phi(t,t_0) = \exp\left(\int_{t_0}^t A(\sigma)d\sigma\right).$$

(b) Find the state transition matrix  $\Phi(t_1, t_0)$  for the matrix

$$A(t) = \begin{bmatrix} \alpha(t) & \beta(t) \\ -\beta(t) & \alpha(t) \end{bmatrix},$$

where  $\alpha(t)$  and  $\beta(t)$  are continuous functions of t.