

Lecture 17

11/13/12

Linear Systems

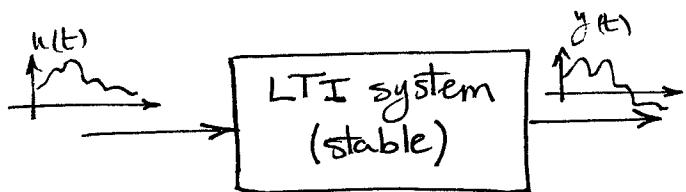
Last time:

- Frequency responses of SISO LTI systems

Today:

- Extensions to MIMO case

L_2 -norm (energy of a signal)



$$\|u\|_2^2 = \int_0^\infty u^T(t) u(t) dt \quad , \quad y(t) = \int_0^t H(t-\tau) u(\tau) d\tau$$



$$Y(j\omega) = H(j\omega) U(j\omega)$$

$$\|y\|_2^2 = \int_0^\infty y^T(t) y(t) dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} Y^*(j\omega) Y(j\omega) d\omega = \dots$$

Parseval's equality

$$\cdots = \frac{1}{2\pi} \int_{-\infty}^{\infty} U^*(j\omega) \underbrace{H(j\omega) H^*(j\omega)}_{\substack{\text{At any } \omega \text{ this is a square} \\ \text{Hermitian matrix} \quad (\text{In SISO case } |H(j\omega)|^2)}} U(j\omega) d\omega$$

Aside!

$$\begin{bmatrix} 1+j \\ 2-j \\ 3+4j \end{bmatrix}^* = [1-j \ 2+j \ 3-4j] \quad \text{In Matlab: } U'$$

If Matrix M is Hermitian $M^* = M$.

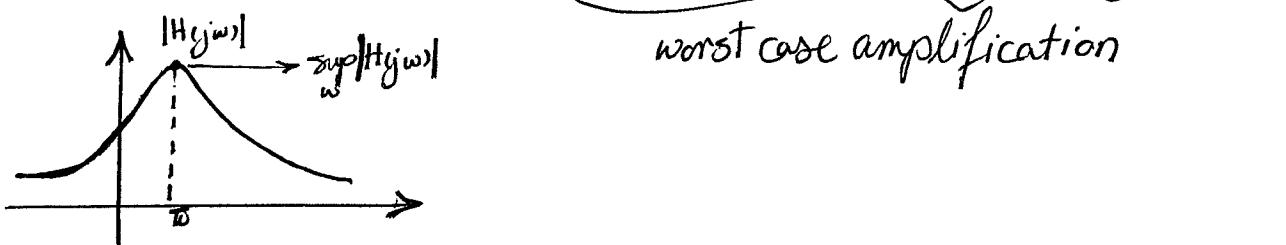
Ex. $(H^*H)^* = H^* \cdot (H^*)^* = H^*H$ so H^*H is Hermitian

$$\text{SISO: } \|y\|_2^2 = \frac{1}{2\pi} \int_{-\infty}^{+\infty} |H(j\omega)|^2 |U(j\omega)|^2 d\omega \leq \sup_{\omega} |H(j\omega)|^2 \cdot \frac{1}{2\pi} \int_{-\infty}^{+\infty} |U(j\omega)|^2 d\omega$$

$$= \sup_{\omega} |H(j\omega)|^2 \cdot \|u\|_2^2$$

$$\Rightarrow \|y\|_2^2 \leq \sup_{\omega} |H(j\omega)|^2 \cdot \|u\|_2^2$$

L_2 norm of the output is upper bounded by the L_2 norm of the input times the largest value on the Bode mag. plot.



In fact, it can be shown that $\sup_{\omega} |H(j\omega)|^2$ is a tight upper bound

(There is a finite energy input st. $\|y\|_2^2 = \sup_{\omega} |H(j\omega)|^2 \|u\|_2^2$)

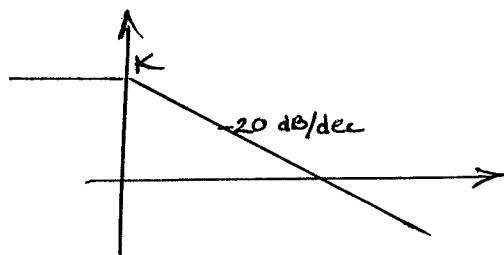
Conclusion: If we limit input signals to be of unit energy, then the worst case [largest] energy that the output can achieve is given by the square of the peak value on the Bode magnitude plot ($\sup_{\omega} |H(j\omega)|^2$)

$$\sup_{\substack{0 < \|u\|_2^2 \leq 1}} \frac{\|y\|_2^2}{\|u\|_2^2} = \text{maximize}_{\substack{\text{finite input} \\ \text{energy}}} \frac{\text{output energy}}{\text{input energy}} = \sup_{\omega} |H(j\omega)|^2$$

Ex $H(s) = \frac{K}{s+1}$

$$H(j\omega) = \frac{K}{j\omega + 1} \Rightarrow |H(j\omega)|^2 = \frac{K^2}{\omega^2 + 1}$$

$$\Rightarrow \sup_{\omega} |H(j\omega)|^2 = |H(j0)|^2 = K^2$$



Big Question : How to generalize this to MIMO case?

Answer : Proper generalization of $\sup_{\omega} |H(j\omega)|^2$ to MIMO case is given by $\sup \sigma_{\max}(H(j\omega))$ where σ_{\max} is the largest singular value of $H(j\omega)$.

A brief overview of SVD (Singular Value Decomposition)

What do we know? e-value decomposition of a square matrix $M \in \mathbb{C}^{n \times n}$

$Mv_i = \lambda_i v_i$. If M is diagonalizable, V is invertible.

then $MV = V\Lambda$

$$\begin{bmatrix} v_1 & \dots & v_n \end{bmatrix} \xrightarrow{\quad} \begin{bmatrix} \lambda_1 & \lambda_2 & \dots & \lambda_n \end{bmatrix}$$

If $M = M^*$ then $M = V\Lambda V^*$

matrix of e-vectors

diagonal of e-values

If a matrix is Hermitian it is unitarily diagonalizable.

What if $M \in \mathbb{C}^{m \times n}$ (rectangular matrix)

A square matrix U is unitary if $UU^* = U^*U = I \Rightarrow U^{-1} = U^*$

$$\|Ux\|_2^2 = (Ux)^*(Ux) = x^* \underbrace{U^*U}_{I} x = \|x\|_2^2$$

vector euclidean norm

Fact Any matrix $M \in \mathbb{C}^{m \times n}$ can be decomposed into

$$m \left\{ \begin{bmatrix} M \\ m \times n \end{bmatrix} \right\} = \left[\begin{array}{c|c} U & \Sigma \\ m \times m & m \times n \end{array} \right] \left[\begin{array}{c|c} V^* & \\ n \times n & \end{array} \right]$$

$$\begin{bmatrix} M \\ m \times n \end{bmatrix} = [U][\Sigma][V^*]$$

$$\left. \begin{aligned} \text{where: } & UU^* = U^*U = I_m \\ & VV^* = V^*V = I_n \end{aligned} \right\} \Rightarrow U, V \text{ unitary}$$

$$\Sigma = \begin{bmatrix} \sigma_1 & & & \\ & \sigma_2 & & \\ & & \ddots & \\ & & & \sigma_r \end{bmatrix} \quad \sigma_1 \geq \sigma_2 \geq \sigma_3 \geq \dots \geq \sigma_r$$

singular values of matrix M

$r = \text{rank}(M)$

Form MM^* and M^*M

$$\boxed{MM^* = U\Sigma V^* (U\Sigma V^*)^* = U\Sigma \underbrace{V^*V}_{I} \Sigma^* V^*}$$

$$= U\Sigma \Sigma^* U^*$$

$$\Rightarrow (MM^*)U = U \cdot \underbrace{\Sigma \Sigma^*}_{\begin{bmatrix} \sigma_1^2 & & 0 \\ & \ddots & \\ 0 & \dots & \sigma_r^2 & 0 \\ & \dots & 0 & \dots & 0 \end{bmatrix}}$$

* thus eigenvalue decomposition of a matrix MM^* gives left singular vectors U_i (columns of matrix U) and corresponding eigenvalues determine $\sigma_1^2, \sigma_2^2, \dots, \sigma_r^2$.

$$M^*M = V\Sigma^* \underbrace{U^*}_{I} \Sigma V^* = V\Sigma^* \Sigma V^*$$

$$\Rightarrow (M^*M)V = V(\Sigma^* \Sigma)$$

$$M^*M \cdot v_i = \sigma_i^2 v_i$$

v_i : right singular vectors

HW: Go to MIT notes,
read about SVD