

Random Processes

⊙ Suppose $x(t)$ is a random process

Then let the **mean function** be defined by

$$\mu_x(t) = E[x(t)]$$

⊙ Define the **Correlation function** as

$$R_x(t_1, t_2) = E[x(t_1)x(t_2)^*]$$

⊙ Define the **Covariance function** as

$$K_x(t_1, t_2) \triangleq E[(x(t_1) - \mu_x(t_1))(x(t_2) - \mu_x(t_2))^*]$$

One can easily show that

$$K_x(t_1, t_2) = R_x(t_1, t_2) - \mu_x(t_1)\mu_x(t_2)$$

Markov Random Process

Definition:

- (a) A continuous-valued Markov process $X(t)$ satisfies

$$f_x(x_n, t_n \mid x_{n-1}, x_{n-2}, \dots, x_1; t_{n-1}, \dots, t_1) \\ = f_x(x_n, t_n \mid x_{n-1}, t_{n-1}) \\ \text{for all } x_1, x_2, \dots, x_n \text{ and for all} \\ t_1 < t_2 < \dots < t_n \text{ and} \\ \text{for all integers } n > 0$$

- (b) A discrete-valued Markov process satisfies

$$P_x(x_n, t_n \mid x_{n-1}, \dots, x_0; t_{n-1}, \dots, t_0) \\ = P_x(x_n, t_n \mid x_{n-1}, t_{n-1}) \\ \text{for all } x_1, \dots, x_n \text{ and } t_1 < t_2 < \dots < t_n \\ \text{for all integers } n > 0.$$

Chapman - Kolmogorov Equations

Consider three times $t_3 > t_2 > t_1$
and Markov process random variables
at these times $x(t_3); x(t_2); x(t_1)$.

Then

$$\begin{aligned} f_x(x_3, x_1; t_3, t_1) &= \int_{-\infty}^{\infty} f_x(x_3, x_2, x_1; t_3, t_2, t_1) dx_2 \\ &= \int_{-\infty}^{\infty} f_x(x_3 | x_2, x_1; t_3, t_2, t_1) \\ &\quad f_x(x_2, x_1; t_2, t_1) dx_2 \end{aligned}$$

$$\begin{aligned} \Rightarrow f_x(x_3 | x_1; t_3, t_1) &= \int_{-\infty}^{\infty} f_x(x_3 | x_2, x_1; t_3, t_2, t_1) f_x(x_2 | x_1; t_2, t_1) dx_2 \\ &= \int_{-\infty}^{\infty} f_x(x_3 | x_2, x_1; t_3, t_2, t_1) f_x(x_2 | x_1; t_2, t_1) dx_2 \end{aligned}$$

$$\Rightarrow f_x(x_3 | x_1; t_3, t_1) = \int_{-\infty}^{\infty} f_x(x_3 | x_2, x_1; t_3, t_2, t_1) f_x(x_2 | x_1; t_2, t_1) dx_2$$

$$\Rightarrow \boxed{f_x(x_3 | x_1) = \int_{-\infty}^{\infty} f_x(x_3 | x_2) f(x_2 | x_1) dx_2}$$

where we have dropped t for convenience.

Linear Systems With random Inputs

Theorem: Let the random process $X(t)$ be the input to a linear system L with output process $Y(t)$. Then the mean function of the output is given as

$$\begin{aligned} E[Y(t)] &= L \{ E[X(t)] \} \\ &= L [M_X(t)] \end{aligned}$$

Proof: By definition

$$Y(t, \xi) = L[X(t, \xi)]$$

$$\begin{aligned} \Rightarrow E[Y(t, \xi)] &= E[L X(t, \xi)] \\ &= L[E(X(t, \xi))] \end{aligned}$$

The last step (Somewhat heuristically) follows as the action of L can be captured by a convolution kernel described the output

$$\int_0^\infty h(t, z) u(z) dz$$

for a deterministic input u

Mean

From which it follows that

$$E\left[L\{X(t, \omega)\}\right] = E\left[\int_{-\infty}^{\infty} h(t, z) X(z, \omega) dz\right]$$

$$= \int_{-\infty}^{\infty} h(t, z) E[X(z, \omega)] dz$$

$$= \int_{-\infty}^{\infty} h(t, z) M_X(z) dz$$

$$= L[M_X(t)].$$

□

Classification

Definitions

Let X and Y be random processes. They are

(a) Uncorrelated if $R_{XY}(t_1, t_2) = \mu_X(t_1)\mu_X(t_2)$
 $\forall t_1, t_2$

(b) orthogonal if $R_{XY}(t_1, t_2) = 0, \forall t_1, t_2$

(c) Independent if for all positive integers n , the n th order pdf of X and Y factors

$$P_{X,Y}(x_1, y_1, x_2, y_2, \dots, x_n, y_n; t_1, t_2, \dots, t_n)$$

$$= P_X(x_1, x_2, \dots, x_n; t_1, t_2, \dots, t_n) \\ P_Y(y_1, \dots, y_n, t_1, t_2, \dots, t_n).$$

Stationary Process

Definition

A random process $X(t)$ is stationary if it has the same n^{th} order distribution as $X(t+T)$ for all T and for all positive n .

Note that for stationary processes

the pdf

$$p(x_1, x_2; t_1, t_2) = p(x_1, x_2; t_1 + T, t_2 + T)$$

and in particular by choosing $T = -t_2$

$$p(x_1, x_2; t_1, t_2) = p(x_1, x_2; t_1 - t_2, 0).$$

which implies

$$R_X(t_1, t_2) = E[X(t_1) X(t_2)^*]$$

$$= E[X(t_1 - t_2) X(0)^*]$$

$$\Rightarrow R_X(t, -t_2, 0)$$

and we can define

$$R_X(\tau) \doteq R_X(\tau, 0) = E[X(t+\tau) X(t)^*] \\ \forall t.$$

Wide Sense Stationarity

Definition:

A process $x(t)$ is wide sense stationary
if

$$E [x(t+z)x(t)] = R(z); \quad -\infty < z < \infty.$$

independent of t

and

$$E [x(t)] = \mu_x \quad \text{a constant}$$

independent of t .

Wide Sense Stationary and Linear Systems

Note that ~~see~~ if $Y(t)$ is the output random process with $X(t)$ a WSS

process as the input to a Linear time-invariant system then

$$\begin{aligned} E[Y(t)] &= L[\mu_X(t)] \\ &= \int_{-\infty}^{\infty} h(\tau) \mu_X(t-\tau) d\tau \\ &= \int_{-\infty}^{\infty} h(\tau) \mu_X d\tau \\ &= \mu_X \int_{-\infty}^{\infty} h(\tau) d\tau \\ &= \mu_X \left(\int_{-\infty}^{\infty} h(\tau) e^{-j\omega\tau} d\tau \right) \Big|_{\omega=0} \\ &= \mu_X H(0) \end{aligned}$$

where $H(\omega)$ is the frequency response representation of the linear system L .

Wide Sense Stationary and Linear Systems

Note that

$$\begin{aligned} R_{XY}(t_1, t_2) &= E[X(t_1) Y^*(t_2)] \\ &= E\left[X(t_1) \int_{-\infty}^{\infty} h^*(z) X^*(t_2 - z) dz\right] \\ &= \int_{-\infty}^{\infty} h^*(z) E[X(t_1) X^*(t_2 - z)] dz \\ &= \int_{-\infty}^{\infty} h^*(z) R_{XX}(t_1, t_2 - z) dz \end{aligned}$$

Similarly

$$R_{YY}(t_1, t_2) = \int_{-\infty}^{\infty} h(z_1) R_{XY}(t_1 - z_1, t_2) dz_1$$

Mean Square Calculus

Sample function Continuity:

$$\lim_{\epsilon \rightarrow 0} x(t + \epsilon, \omega) = x(t) \quad \forall \omega.$$

Almost Sure Continuity

$$P \left[\lim_{s \rightarrow t} x(s) \neq x(t) \right] = 0$$

P-Continuity:

$$\lim_{\delta \rightarrow 0} P[|x(s) - x(t)| > \epsilon] = 0$$

for each $\epsilon > 0$.

Continuity in the Mean Square Sense.

Definition:

A random process $X(t)$ is continuous in the mean square sense at the point t if

$$E[|X(t+\epsilon) - X(t)|^2] \rightarrow 0$$

as $\epsilon \rightarrow 0$.

If the above holds for all t
then $X(t)$ is mean square continuous

Mean Square Continuous

Theorem: The random process $X(t)$ is m.s. continuous if and only if

$R_X(t_1, t_2)$ is continuous at the point (t, t) for all t .

Proof:

$$\begin{aligned} & E [| X(t+\epsilon) - X(t) |^2] \\ &= E [X(t+\epsilon) X^*(t+\epsilon)] + E [X(t) X^*(t)] \\ &\quad - E [X(t+\epsilon) X^*(t)] \\ &\quad - E [X(t) X^*(t+\epsilon)] \\ &= R_X(t+\epsilon, t+\epsilon) + R_X(t) \\ &\quad - R_X(t+\epsilon, t) - R_X(t, t+\epsilon) \end{aligned}$$

\therefore The theorem follows.

Mean Square Continuity

Corollary: A wide sense r. process is

m.-s. continuous for all t if and
only if $R_x(\tau)$ is continuous at $\tau=0$.

Mean Square differentiability

The random process $X(t)$ has a mean square derivative at t if the limit

$$\frac{X(t+\epsilon) - X(t)}{\epsilon}$$

has a mean square limit.

i.e. $\exists I$ such that

$$E \left[\left(\frac{X(t+\epsilon) - X(t)}{\epsilon} - I \right)^2 \right]$$

↓
0

as $\epsilon \rightarrow 0$.

Theorem: A random process $X(t)$ with autocorrelation $R_X(t_1, t_2)$ has a m.s. derivative at time t if and only if

$$\frac{\partial^2 R_X(t_1, t_2)}{\partial t_1 \partial t_2} \text{ exists at } t_1 = t_2 = t.$$

Mean Square derivative

Theorem: If a random process $x(t)$ with mean function $M_x(t)$ and correlation function $R_x(t_1, t_2)$ has a m.-s derivative $x'(t)$ then the mean and correlation functions of $x'(t)$ are given by

$$M_{x'}(t) = \frac{dM_x(t)}{dt}$$

$$R_{x'}(t_1, t_2) = \frac{\partial^2 R_x(t_1, t_2)}{\partial t_1 \partial t_2}$$

⊛ Note that we have seen earlier that
 If $X(t)$ is a Wiener process then

$$R_X(t_1, t_2) = E[X(t_1)X(t_2)] = \min(t_1, t_2) \cdot \alpha$$

$$\text{and } E(X(t)) = 0 \quad \forall t$$

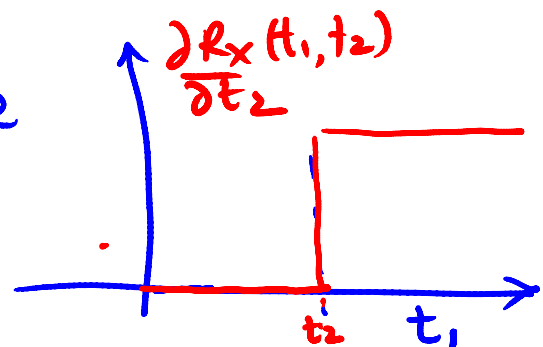
(This was a HW problem).

Clearly

$$\begin{aligned} \frac{\partial R_X(t_1, t_2)}{\partial t_2} &= \frac{\partial}{\partial t_2} (\alpha t_2) && \text{if } t_2 < t_1 \\ &= \frac{\partial}{\partial t_2} (\alpha t_1) && \text{if } t_1 < t_2 \end{aligned}$$

$$\therefore \frac{\partial R_X(t_1, t_2)}{\partial t_2} = \begin{cases} \alpha & \text{if } t_2 < t_1 \\ 0 & \text{if } t_1 < t_2 \end{cases}$$

which has a shape
 as a function of t_1



Therefore

$$\frac{\partial R_x(t_1, t_2)}{\partial t_2} = \alpha u(t_1 - t_2)$$

as a function t_1 and t_2
fixed

$$\therefore \frac{\partial R_x(t_1, t_2)}{\partial t_1 \partial t_2} = \alpha \frac{\partial}{\partial t_1} u(t_1 - t_2)$$

$$= \alpha \delta(t_1 - t_2).$$

The generalized m-s derivative of Wiener process is called white noise and from an earlier theorem

$$R_{x'}(t_1, t_2) = \frac{\partial R_x(t_1, t_2)}{\partial t_1 \partial t_2} = \alpha \delta(t_1 - t_2)$$

WSS processes and psd; Wiener-Khinchin Relation

Suppose $X(t)$ is a W.S.S. process
with

$$R_{XX}(z) \doteq R_{XX}(z, 0) = R_{XX}(t+z, t)$$

WIENER-KHINCHIN Relationship.

Then define

$$S_{XX}(\omega) = \int_{-\infty}^{\infty} R_{XX}(z) e^{-j\omega z} dz$$

i.e. $S_{XX}(\omega) = \text{FT}(R_{XX})$

and

$$R_{XX}(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} S_{XX}(\omega) e^{j\omega t} d\omega$$

i.e. $R_{XX} = \text{IFT}(S_{XX})$

Now suppose $Y(t) = L[X(t)]$

defined by

$$Y(t, \xi) = \int_{-\infty}^{\infty} h(\tau) X(t-\tau, \xi) d\tau$$

Power Spectral density

$$R_{YX}(\tau) = E[Y(t+\tau) \hat{X}(t)]$$

$$= E\left[\int_{-\infty}^{\infty} h(t+\tau-\alpha) X(\alpha) d\alpha \hat{X}(t)\right]$$

$$= \int_{-\infty}^{\infty} h(t+\tau-\alpha) E(X(\alpha) \hat{X}(t)) d\alpha$$

$$= \int_{-\infty}^{\infty} h(t+\tau-\alpha) R_{XX}(t-\alpha) d\alpha$$

$$= \int_{-\infty}^{\infty} h(\tau-\alpha') R_{XX}(\alpha') d\alpha'$$

$$= h(\tau) * R_{XX}(\tau)$$

Power spectral density

Then

$$S_{YY}(\omega) = \int_{-\infty}^{\infty} R_{YY}(\tau) e^{-j\omega\tau} d\tau$$

Now,

$$R_{YY}(\tau) = E[Y(t+\tau)Y^*(t)]$$

$$= E\left[Y(t+\tau) \int_{-\infty}^{\infty} X^*(t-\alpha) h(\alpha) d\alpha\right]$$

$$= \int_{-\infty}^{\infty} E[Y(t+\tau) X^*(t-\alpha) h(\alpha)] d\alpha$$

$$= \int_{-\infty}^{\infty} R_{YX}(\tau+\alpha) h^*(\alpha) d\alpha$$

$$= \int_{-\infty}^{\infty} R_{YX}(\tau-\beta) h^*(-\beta) d\beta$$

$$= R_{YX}(\tau) * h^*(-\tau)$$

We have shown that

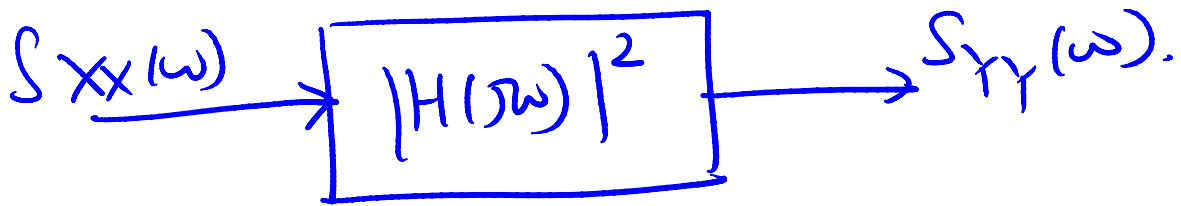
$$R_{YX}(\tau) = h(\tau) * R_{YX}(\tau)$$

$$\therefore R_{YY}(\tau) = h(\tau) * R_{YX}(\tau) * h^*(-\tau)$$

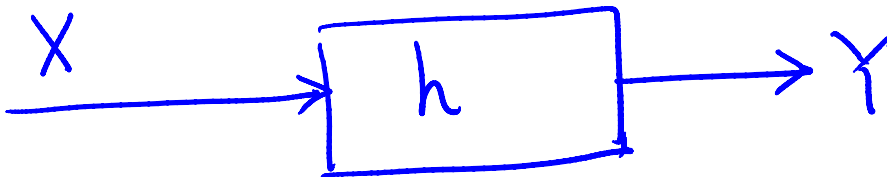
Power Spectral Density

$$\begin{aligned} \therefore S_{YY}(\omega) &= H(\omega) S_{XX}(\omega) H^*(\omega) \\ &= |H(\omega)|^2 S_{XX}(\omega) \end{aligned}$$

Thus



if



$$Y = h * X.$$

White noise input

Evidently if the input is white noise

$$R_x(\tau) = \delta(\tau)$$

$$\Rightarrow S_{xx}(\omega) = 1$$

and

$$S_{yy}(\omega) = |H(\omega)|^2$$

—x—

Why is it power Spectral density

Theorem: Let $X(t)$ be a stationary random process with finite variance, autocorrelation function $R(\tau)$ and power spectral density $S_X(\omega)$. Then $S_X(\omega) \geq 0$

and for $\omega_2 \gg \omega_1$,

$\frac{1}{2\pi} \int_{\omega_1}^{\omega_2} S_X(\omega) d\omega$ is the average power of $X(t)$ in the frequency band (ω_1, ω_2)

Proof: Define a filter H such that

$$\begin{aligned} H(\omega) &= 0 & \text{if } \omega \notin [\omega_1, \omega_2] \\ &= 1 & \text{if } \omega \in [\omega_1, \omega_2] \end{aligned}$$

Suppose $Y(t)$ is the output of the filter with $X(t)$ the input. Then from the theorem we have proven

Why is it psd

$$S_{YY}(\omega) = S_{XX}(\omega) \quad \text{if } \omega \in [\omega_1, \omega_2]$$
$$= 0 \quad \text{otherwise.}$$

and the autocorrelation function

$$R_Y(\tau) = \frac{1}{2\pi} \int_{-\infty}^{\infty} S_{YY}(\omega) e^{j\omega\tau} d\omega$$

and in particular

$$0 \leq E[Y(t)Y(t)] = R_Y(0)$$
$$= \frac{1}{2\pi} \int_{-\infty}^{\infty} S_{YY}(\omega) d\omega$$
$$= \frac{1}{2\pi} \int_{\omega_1}^{\omega_2} S_{XX}(\omega) d\omega$$

\therefore The output of a filter that retains only the frequencies between (ω_1, ω_2)

has average power $\frac{1}{2\pi} \int_{\omega_1}^{\omega_2} S_{XX}(\omega) d\omega$

In particular the average power in the

1

why call it psd

the frequency range $(\omega, \omega + \Delta\omega)$ is

$$\frac{1}{2\pi} \int_{\omega}^{\omega + \Delta\omega} S_{xx}(\omega') d\omega' \geq 0$$

$$\approx \frac{1}{2\pi} S_{xx}(\omega) \Delta\omega \geq 0$$

$$\therefore S_{xx}(\omega) \geq 0$$

and the power density of $x(t)$

at the frequency ω is

$$S_{xx}(\omega).$$

Remark:

One can start with the definition of $S_{xx}(\omega)$ as the average power of x in the frequency range $(\omega, \omega + \Delta\omega)$ and prove that

$S_{xx}(\omega)$ is the Fourier transform of the autocorrelation function. This what is done in physics books and is called the Wiener-Khinchin theorem

Examples

Consider the stochastic process generated

by

$$Y(t+dt) - Y(t) = -\alpha Y(t) dt + \underbrace{\sqrt{dt} N(0, dt)}_{dw_t}$$

↑
wiener process

⇒ Symbolically this can be rewritten as

$$\frac{Y(t+dt) - Y(t)}{dt} = -\alpha Y(t) + \frac{dw_t}{dt}$$

$$\Rightarrow \frac{dY(t)}{dt} = -\alpha Y(t) + n(t)$$

where $n(t)$ is white noise (the derivative of wiener process)

$$\Rightarrow \frac{dY(t)}{dt} + \alpha Y(t) = n(t);$$

Assume $\alpha > 0$.

Then $n(t)$ is white noise.

Note that we have shown earlier that the wiener process

Examples

has mean $\langle W(t) \rangle = 0$

and Variance $\langle W^2(t) \rangle = t$

and $R_{WW}(t_1, t_2) = \min(t_1, t_2)$.

\therefore as n is the derivative of the Wiener process we have

$$\begin{aligned}\langle n(t) \rangle &= \frac{d\langle W(t) \rangle}{dt} \\ &= 0\end{aligned}$$

and $R_{nn}(t_1, t_2) = \delta(t_1 - t_2)$

↑ established earlier.

Thus, $n(t)$ is wide sense stationary with mean 0 and autocorrelation

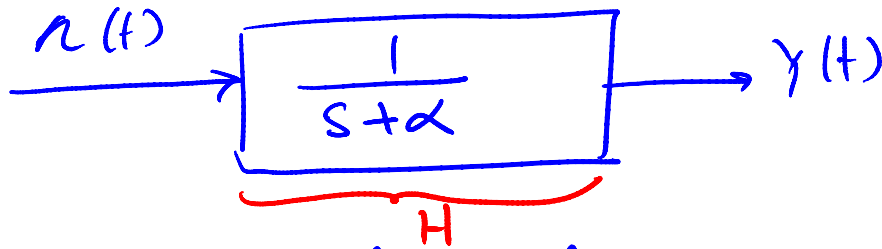
$$R_n(\tau) = \delta(\tau).$$

Coming back to the stochastic differential equation

$$\frac{dY(t)}{dt} + \alpha Y(t) = n(t)$$

Example

The filter corresponding to the above equation is



and in the fourier domain

$$H(j\omega) = \frac{1}{\alpha + j\omega}$$

$$\Rightarrow H(j\omega) = \frac{\alpha - j\omega}{\alpha^2 + \omega^2}$$

$$= \frac{\alpha}{\alpha^2 + \omega^2} - j \frac{\omega}{\alpha^2 + \omega^2}$$

$$\Rightarrow |H(j\omega)|^2 = \frac{\alpha^2}{(\alpha^2 + \omega^2)^2} + \frac{\omega^2}{(\alpha^2 + \omega^2)^2}$$

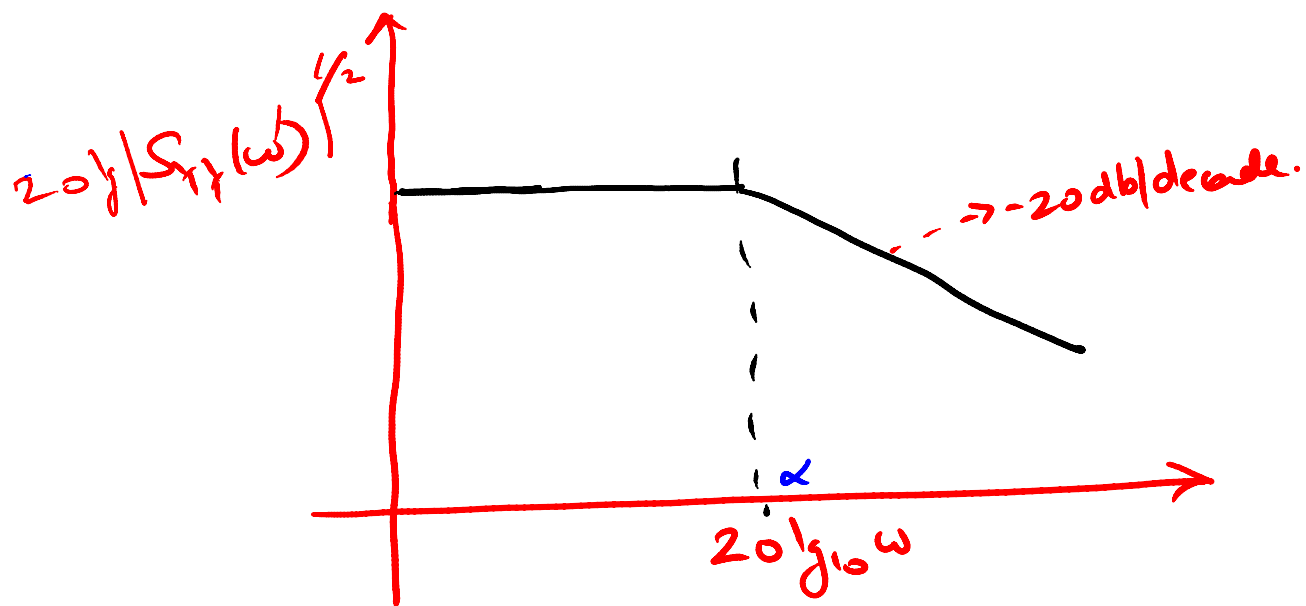
$$= \frac{1}{(\alpha^2 + \omega^2)}$$

$$\therefore \text{Now, } S_{yy}(\omega) = \frac{1}{\alpha^2 + \omega^2} \quad S_{xx}(\omega) = \frac{1}{\alpha^2 + \omega^2}$$

Example

Thus, y has a Spectral density

$$S_{yy}(\omega) = \frac{1}{\alpha^2 + \omega^2} = \frac{1}{\alpha^2} \frac{1}{\left(\frac{\omega}{\alpha}\right)^2 + 1}$$



$$20 \log_{10} |S_{yy}(\omega)|^{1/2} = +20 \log_{10} \sqrt{\frac{1}{\alpha^2 \left(\left(\frac{\omega}{\alpha}\right)^2 + 1\right)}}$$

$$= 20 \log_{10} \frac{1}{\alpha} - 20 \log_{10} \sqrt{\left(\frac{\omega}{\alpha}\right)^2 + 1}$$

\therefore for $\omega \ll \alpha$

$$20 \log_{10} |S_{yy}(\omega)|^{1/2} = -20 \log_{10} \alpha$$

$$\omega > \alpha \quad 20 \log_{10} |S_{yy}(\omega)|^{1/2} = -20 \log_{10} \alpha - 20 \log_{10} \omega$$

α can be easily determined from the corner frequency.