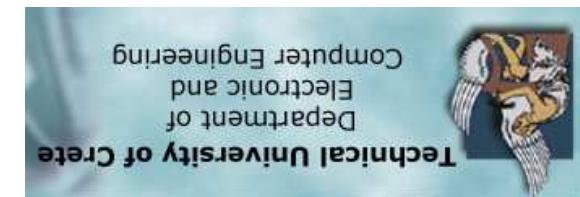


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LOW-Rank Decomposition of Multi-Way Arrays: A Signal Processing Perspective



- Introduction & motivating list of applications
- 3-way arrays: similarities and differences with matrices
- Rank, and low-rank decomposition; 3-way notation
- Closer look at applications: Data modeling
- Uniqueness
- Algorithms
- Performance
- Web pointers
- What lies ahead & wrap-up

Contents

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- Sponsors: NSF CCR 9733540, 0096165, 9979295, 0096164; ONR N/N00014-99-1-0693; DARPA/ATO MDA 972-01-0056; ARL C & N CTA Cooperative Agreement DADD19-01-2-0011

Acknowledgements

scaling

- Exploratory data analysis: clustering, scatter plots, multi-dimensional
- 3-D Radar clutter modeling and mitigation
- Blind decoding of a class of linear space-time codes
- estimation and wireless channel sounding
- Multi-dimensional harmonic retrieval w/ applications in DOA
- to CFO, using receive diversity
- Joint detection-estimation in SIMO/MIMO OFDM systems subject
- Multiple-invariance sensor array processing (MI-SAP)
- antenna array
- Blind multiuser detection-estimation in DS-CDMA, using Rx

List of Applications - I

- Chromatography, spectroscopy, magnetic resonance, ...
- Analyses of individual differences (Psychology)
- HOS-based parameter estimation and signal separation
("super-symmetric")
- iii) ACMA
- ii) Blind source separation for multi-channel speech signals
time-varying power loading, spectral color / multiple lags
- i) Blind spatial signature estimation from covariance matrices, using joint diagonalization problems (symmetric):

List of Applications - II

- attribute \times sample), personality traits ...
- Spectroscopy, NMR, Radar, analysis of food attributes (judge \times
- Multiuser MIMO-OFDM: antenna \times FFT bin \times symbol
- MI SAP: subarray \times element \times snapshot
- CDMA w/ Rx Ant array @ baseband: chip \times symbol \times antenna
- Three-way arrays: $[x_{i,j,k}] : (I \times J \times K)$
- Two-way arrays, AKA matrices: $\mathbf{X} := [x_{i,j}] : (I \times J)$

Three-Way Arrays

- Rank := smallest number of rank-one „factors“ („terms“ is probably better) for exact additive decomposition (same concept for both 2-way and 3-way)
- Two-way rank-one factor: rank-one MATRIX outer product of 2 vectors (containing all double products)
- Three-way rank-one factor: rank-one 3-WAY ARRAY outer product of 3 vectors (containing all triple products) - same concept

Three-Way vs Two-Way Arrays - Similarities

- complexity theory*, Springer, Berlin, 1997]
- decomposition over C [Burgisser, Clausen, Shokrollahi, Algebraic missing for decomposition over R ; theory more developed for ten Berge], general results for maximal rank and typical rank sorely 3-way: Except for loose bounds and special cases [Kruskal; J.M.F. □
- Closed (R versus C); 3-way: rank sensitive to R versus C □
- 2-way: rank insensitive to whether or not underlying field is open or □
- Three-way: $\text{rank}(\text{rand}(2,2,2))$ is a RV (2 w.p. 0.3, 3 w.p. 0.7) □
- Two-way: $\text{rank}(\text{rand}(I,J)) = \min(I,J)$ w.p. 1; □
- Three-way: row-rank \neq column-rank \neq "tube"-rank \neq rank □
- Two-way ($I \times J$): row-rank = column-rank = rank $\leq \min(I,J)$; □

Three-Way vs Two-Way Arrays - Differences

$$\mathbf{A} \odot (\mathbf{B} \odot \mathbf{C}) = (\mathbf{A} \odot \mathbf{B}) \odot \mathbf{C}$$

$$vec(\mathbf{ADB}_T) = (\mathbf{B} \odot \mathbf{A}) \mathbf{d}(\mathbf{D})$$

$$\mathbf{A} = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}, \quad \mathbf{B} = \begin{bmatrix} 5 & 10 \\ 15 & 20 \end{bmatrix}, \quad \mathbf{A} \odot \mathbf{B} = \begin{bmatrix} 5 & 20 \\ 15 & 30 \end{bmatrix} \quad 25 \quad 30 \\ 15 \quad 40 \\ 45 \quad 80 \\ 75 \quad 120$$

☞ Column-wise Kronecker Product:

Khatri-Rao Product

$$\mathbf{x}_{KII} := \text{vec} \left(\mathbf{X}_{KII} \right) = (\mathbf{A} \odot (\mathbf{B} \odot \mathbf{C})) \mathbf{1}_{F \times 1} = \left((\mathbf{A} \odot \mathbf{B} \odot \mathbf{C}) \mathbf{1}_F \right) \mathbf{1}_{F \times 1}$$

- Vector:

$$(\mathbf{B} \odot \mathbf{C}) \mathbf{A}_T = \mathbf{X}_{KII}$$

- Matrix:

$$\mathbf{X}^k = \mathbf{A} \mathbf{D}^k (\mathbf{C}) \mathbf{B}_T, \quad k = 1, \dots, K$$

- Slabs:

$$x^{i,j,k} = \sum_{f=1}^F a^{i,f} q^{j,f} c^{k,f}, \quad i = 1, \dots, I, \quad j = 1, \dots, J, \quad k = 1, \dots, K$$

- Scalar:

LRD of Three-Way Arrays: Notation

$$\mathbf{A}^{(N)} \otimes \cdots \otimes \mathbf{A}^{(2)} \otimes \mathbf{A}^{(1)} \left(\mathbf{1}_{F \times 1} \right)$$

$$= \left(\mathbf{X}_{I_1 I_2 \cdots I_{N-1} \times I_N} \right)_{(N \times 1)} =: \mathbf{vec}(\mathbf{X})$$

- Vector:

$$\mathbf{A}^{(N)} \otimes \cdots \otimes \mathbf{A}^{(2)} \otimes \mathbf{A}^{(1)} = \mathbf{X}_{(I_1 I_2 \cdots I_{N-1} \times I_N)}$$

- Matrix:

$$a_{i_1 \cdots i_N} = \sum_{f=1}^F \prod_{n=1}^N x_{i_1 \cdots i_n}$$

- Scalar:

LRD of N-Way Arrays: Notation

$$\mathbf{R}^k = \mathbf{A}\mathbf{D}^k(\mathbf{P})\mathbf{A}_H^T, k = 1, \dots, K$$

PARAFAC/CANDECOMP (INDSCAL):

- Blind signature estimation from covariance data: Symmetric

$$\mathbf{X}^k = \mathbf{A}\mathbf{D}^k(\mathbf{C})\mathbf{B}_T^T, k = 1, \dots, K$$

displaced but otherwise identical subarray:

- matrix (usually denoted \mathbf{S}), $\mathbf{D}^k(\mathbf{C})$ holds the phase shifts for the k -th
- matrix (\mathbf{B}_T^T) is temporal signal

$$x_{i,j,k} = \sum_{f=1}^F a_{i,f} q_{j,f} c_{k,f}, \quad i = 1, \dots, I, \quad j = 1, \dots, J, \quad k = 1, \dots, K$$

- CDMA: (i, j, k, f) : (Rx antenna, symbol snapshot, chip, user)

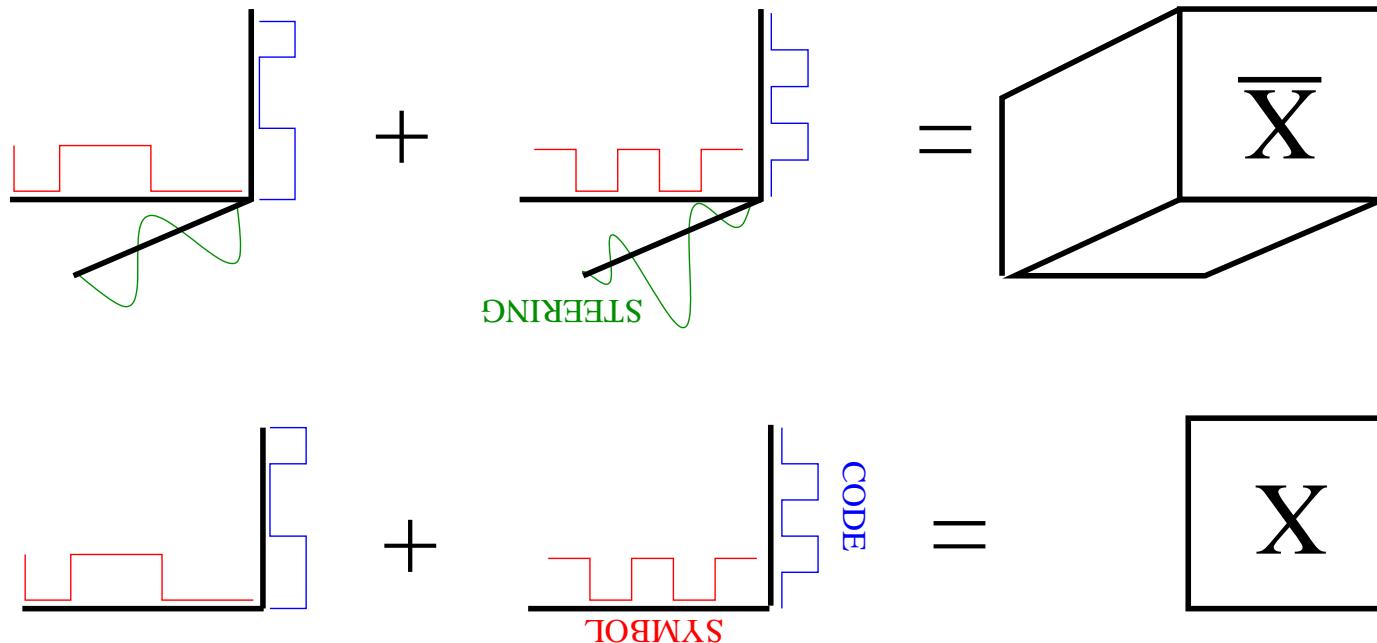
Closer look at applications: Data modeling

is unique under certain conditions

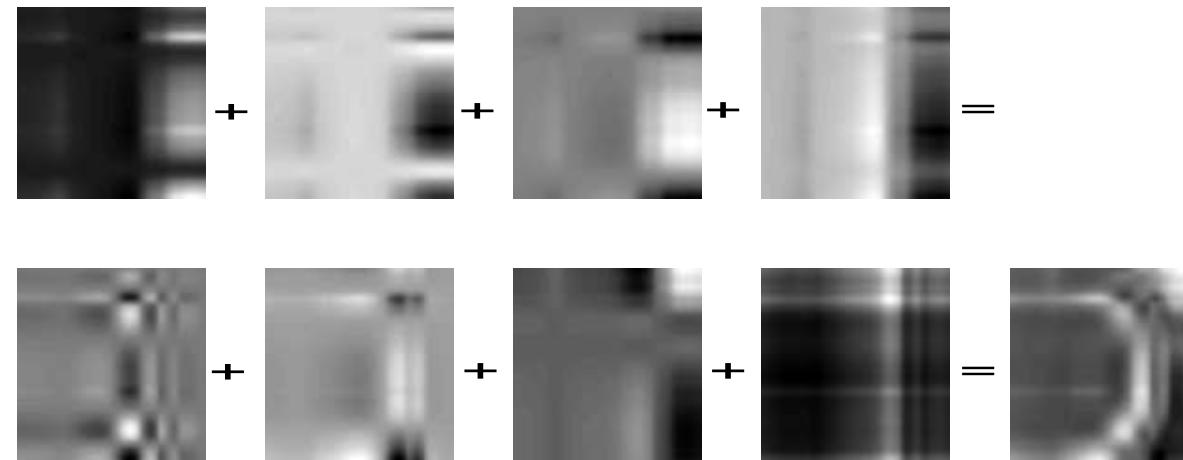
- Fact 2: Low-rank 3- and higher-way array decomposition (PARAFAC)

for rank > 1

- Fact 1: Low-rank matrix (2-way array) decomposition not unique



Early Take-Home Point



$$\sum_{k=1}^K a_{i,k} q_{j,k} = x_{i,j}$$

$$X = AB^T = a_1 b_1^T + \dots + a_K b_K^T$$

LBD of Matrices: Rotational Indeterminacy

→ Can only guess recipe



Reverse engineering of soup?

☞ Same ingredients, different proportions → recipe!



Sample from two or more Cooks!

- non-blind MMSE clairvoyant Rx
- coherence), relaxed ID conditions, performance within 2 dB from channel sample sizes (channel
- Deterministic approach, works with small sample sizes (channel

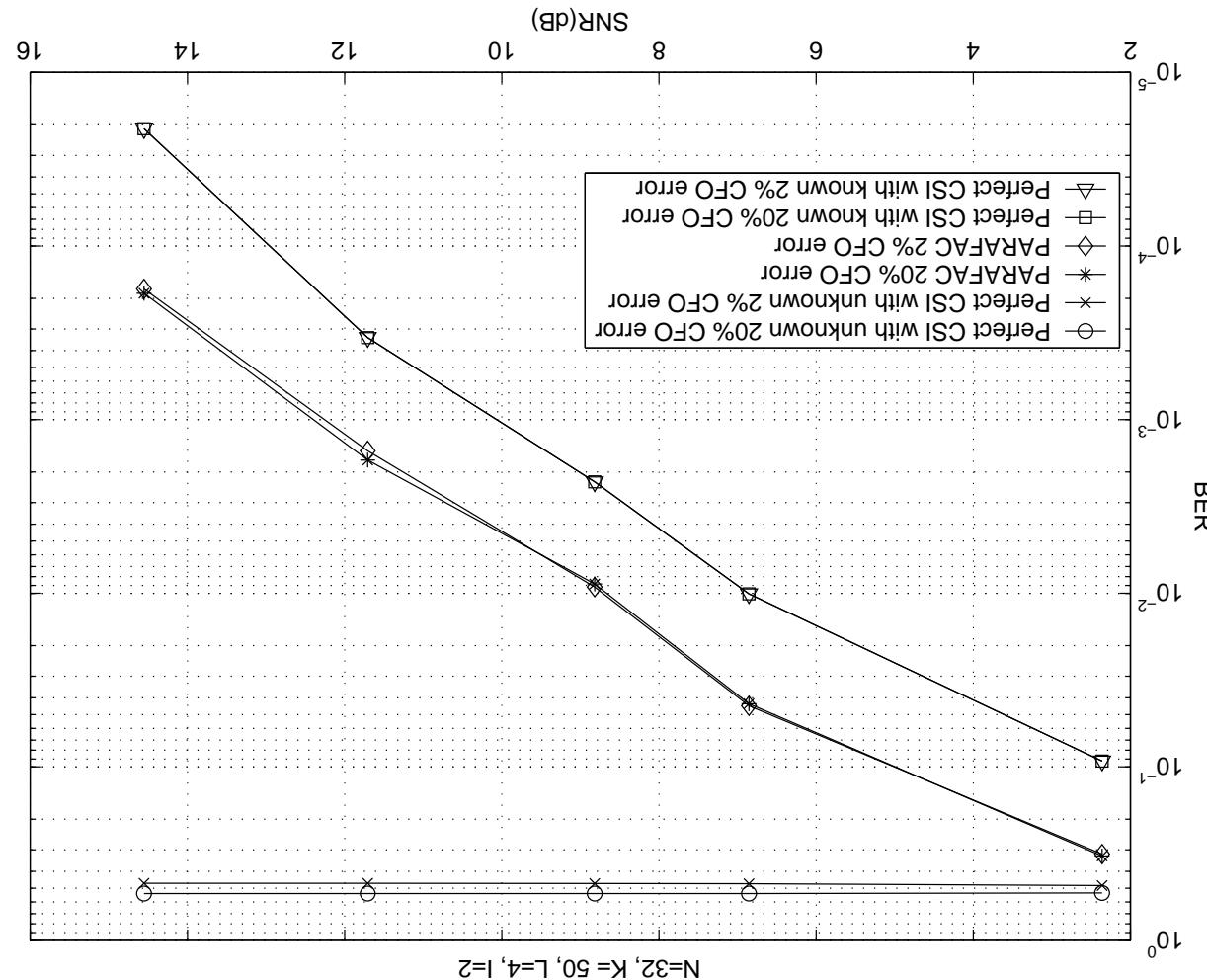
[Jiang & Sidiropoulos, '02]

- PARAFAC model (w/ special structure) \Leftarrow blindly identifiable

$$\mathbf{Y}^i = \mathbf{P}\mathbf{F}_H\mathbf{H}^i(\mathbf{Q}\mathbf{S})_T + \mathbf{W}^i := \mathbf{A}\mathbf{D}^i\mathbf{B}_T^i + \mathbf{W}^i, i = 1, \dots, I$$

- Collect K OFDM symbol snapshots

SIMO OFDM / CFO



SIMO-OFDM / CFO - results

$$\sum_{n=1}^N k-ranks \geq 2F + (N-1)$$

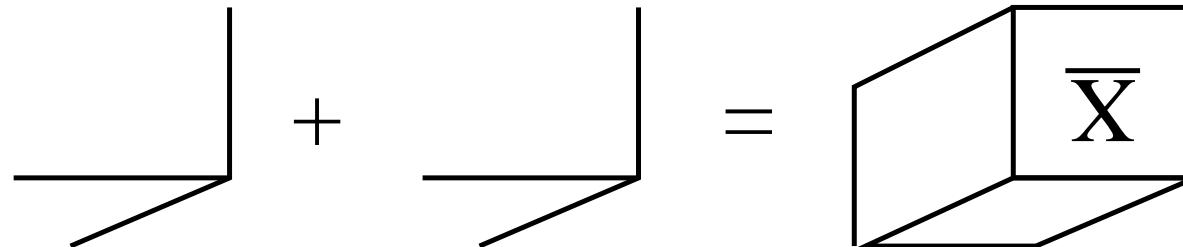
☞ [Sidiropoulos & Bro, J. Chem., 2000]: any N, C :

☞ [Sidiropoulos et al, IEEE TSP, 2000]: $N = 3, C$

(\leq rank)

k -rank = maximum r such that every r columns are linearly independent

☞ [Kruskal, 1977], $N = 3, R$: $k_A + k_B + k_C \geq 2F + 2$



Uniqueness

& Sidiroopoulos, TSP:04]

pinv); but the result is very deep and difficult for fat matrices - see [Jiang
易] Easy to show for a pair of square nonsingular matrices (use rows of

matrix \underline{P} and a non-singular diagonal matrix \underline{D} such that $\underline{A} = \underline{A}\underline{P}\underline{D}$.
then $\underline{F} \leq \underline{F}$; if also $\underline{F} \geq \underline{F}$, then $\underline{F} = \underline{F}$, and there exist a permutation

$$w(\underline{\mathbf{x}}^H \underline{\mathbf{A}}) \geq w(\underline{\mathbf{A}})$$

we have

$$w(\underline{\mathbf{x}}^H \underline{\mathbf{A}}) \leq F - r_{\underline{\mathbf{A}}} + 1,$$

nonzero elements) of its argument. If for any vector \mathbf{x} such that
having no zero column, and $\underline{\mathbf{A}}(I \times \underline{F})$. Let $w(\cdot)$ be the weight (# of
Kruskal's Permutation Lemma [Kruskal, 1977]: Consider $\mathbf{A}(I \times F)$

Key-I

$$k^{\mathbf{B} \odot \mathbf{A}} = 0$$

whereas if $k^{\mathbf{A}} = 0$ or $k^{\mathbf{B}} = 0$

$$k^{\mathbf{B} \odot \mathbf{A}} \geq \min(k^{\mathbf{A}} + k^{\mathbf{B}} - 1, F).$$

If $k^{\mathbf{A}} \geq 1$ and $k^{\mathbf{B}} \geq 1$, then it holds that

☞ **Property:** [Siddropoulos & Liu, 1999; Siddropoulos & Bro, 2000]

Key-II

Stepping stone

☞ A proof of Kruskal's result is beyond our scope. The following is more palatable & conveys flavor (see SAM2004 paper for compact proof):

Theorem: Given $\bar{X} = (A, B, C)$, with $A : I \times F$, $B : J \times F$, and $C : K \times F$, it is necessary for uniqueness of A, B, C that $\min(r_{A \odot B}, r_{C \odot A}, r_{B \odot C}) = F$. If $F > 1$, then it is also necessary that $\min(k_A, k_B, k_C) \geq 2$.

If, in addition $r_C = F$, and $k_A + k_B \geq F + 2$, then A, B , and C are unique up to permutation and scaling of columns, meaning that if $\bar{X} = (\underline{A}, \underline{B}, \underline{C})$, for some $\underline{A} : I \times F$, $\underline{B} : J \times F$, and $\underline{C} : K \times F$, then there exists a permutation matrix L and diagonal scaling matrices V_1, V_2, V_3 such that

$$\underline{A} = A L V_1, \underline{B} = B L V_2, \underline{C} = C L V_3, V_1 V_2 V_3 = I.$$

can be written as KRP of two vectors

No linear combination of two or more columns of $\mathbf{A} \odot \mathbf{B}$

be necessary and sufficient:

puzzle: E.g., for $r\mathbf{C} = \mathbf{F}$, the following condition has been proven to

Jiang & Sidiropoulos '03: new insights that explain part of the

no for $F > 3$

ten Berge & Sidiropoulos, *Psychometrika*, 2002: Yes for $F \in \{2, 3\}$,

Long-held conjecture (Kruskal '89): Yes

Is Kruskal's Condition Necessary?

- Resulting ID conditions beat anything published to date
- Hence if the number of users/sources/Tx is not too big, completely blind identification is possible
- In multiuser MIMO-OFDM, each Tx antenna contributes rank-1 factor
- In MI-SAP application, each source contributes a rank-1 factor
- In CDMA application, each user contributes a rank-1 factor
- So, LRD for 3- or higher-way arrays unique, provided rank is “low enough”; often works for rank $<> 1$

Why Care?

- ❑ ALS —> monotone convergence, usually to global minimum (uniqueness), close to CRB for $F \ll IJK$
- ❑ Workhorse: ALS [Harsman, 1970]: LS-driven (ML for AWGN), iterative, initialized using 2-slab solution or multiple random cold starts
- ❑ SVD/EVD or TLS 2-slab solution (similar to ESPRIT) in some cases (but conditions for this to work are restrictive)

Algorithms

circular fashion until convergence in fit (guaranteed)

- Similarly for the CLS updates of \mathbf{B} , \mathbf{C} (symmetry); repeat in a

$$\mathbf{A}_{CLS} = \left((\mathbf{B} \odot \mathbf{C})_+ \mathbf{X}^{(K_I \times I)} \right)^T$$

\mathbf{A} :

- Given interim estimates of \mathbf{B} , \mathbf{C} , solve for conditional LS update of

$$\mathbf{X}^{(K_I \times I)} = (\mathbf{B} \odot \mathbf{C}) \mathbf{A}_T$$

- ALS is based on matrix view:

Algorithms

- conditions
Sidiropoulos, JASP/MART 2003]; or under very restrictive rank
- Possible if e.g., a subset of columns in A is known [Jiang &
 - In general, no "algebraic" solution like SVD
 - G-N converges faster than ALS, but it may fail
 - ESPRIT-like, ...
 - COMFAC (Tucker3 compression), G-N, Levenberg, ATL3, DT3D,
 - Alt: rank-1 updates possible [Kroonenberg], but inferior
 - ALS initialization matters, not crucial for heavily over-determined problems

Algorithms

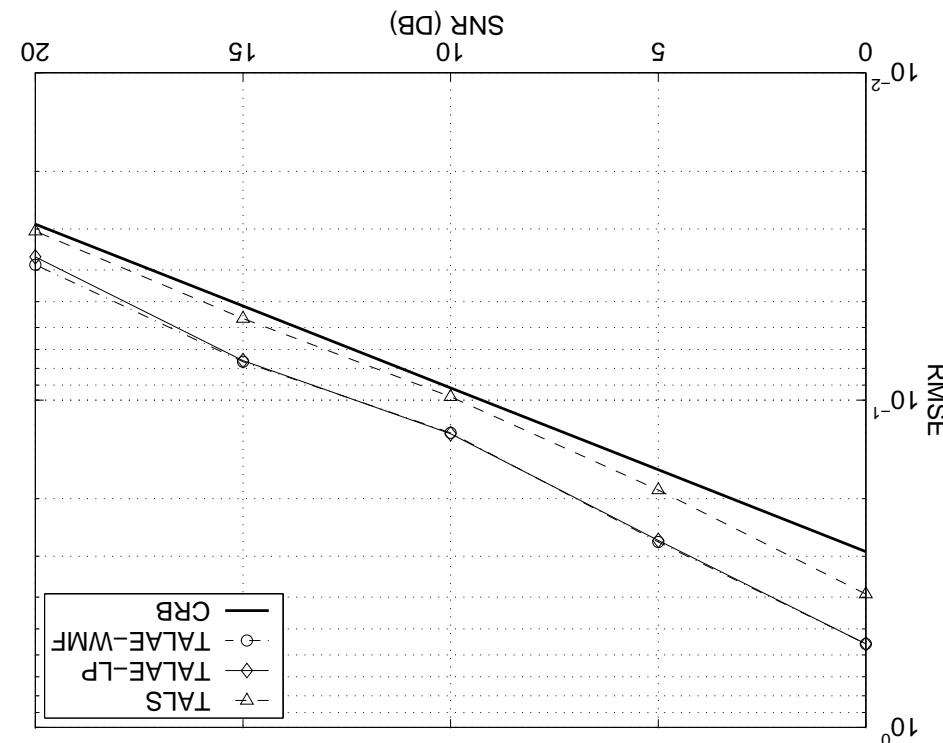
- Least Absolute Error (LAE) criterion: optimal (ML) for Laplacian, Cauchy-distributed errors, outliers robust across α -stable
- Similar to ALS, each conditional matrix update can be shown equivalent to a LP problem \longrightarrow alternating LP [Vorobiov, Rong, Sidiropoulos, Gershman, 2003]
- Alternatively, very simple element-wise updating using weighted median filtering [Vorobiov, Rong, Sidiropoulos, Gershman, 2003]
- Robust algorithms perform well for Laplacian, Cauchy, and not far from optimal in the Gaussian case

Robust Regression Algorithms

- Dependence on how scale-permutation ambiguity is resolved
- Real i.i.d. Gaussian, 3-way, Complex circularly symmetric i.i.d.
- Gaussian, 3-way & 4-way [Liu & Sidiropoulos, TSP 2001]
- Compact expressions for complex 3-way case & asymptotic CRB when one mode length goes to infinity [Jiang & Sidiropoulos, JASP/MART:04]
- Laplacian, Cauchy [Vorobyov, Rong, Sidiropoulos, Gershman, TSP:04] - scaled versions of the Gaussian CRB; scaling parameter only dependent on noise pdf

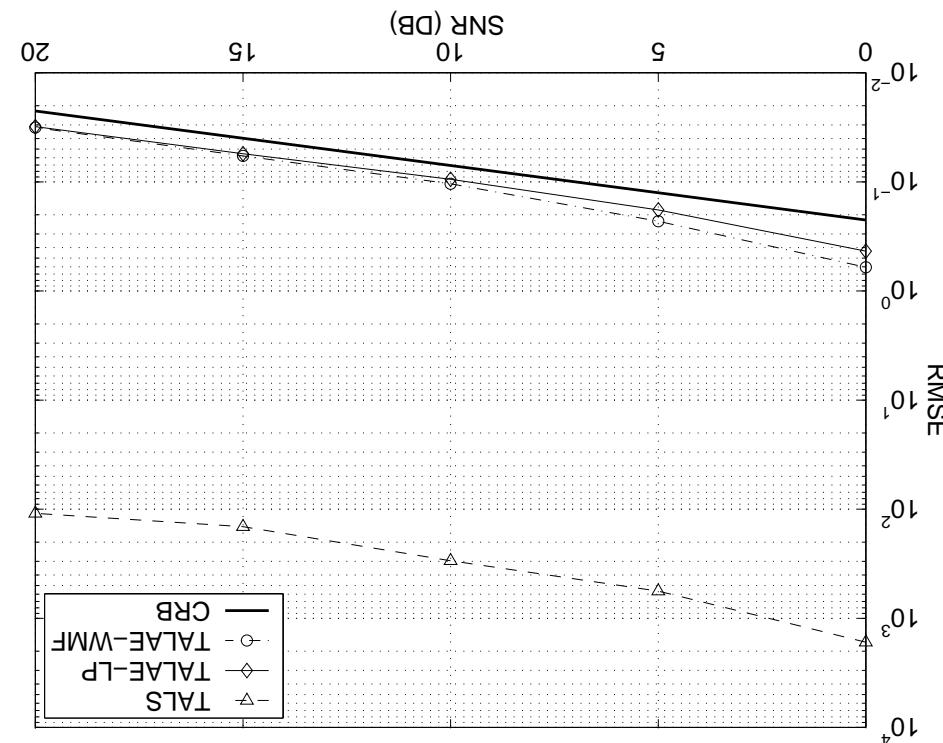
CRBs for the PARAFAC model

Figure 1: RMSEs versus SNR: Gaussian noise, $8 \times 8 \times 20$, $F = 2$



Performance

Figure 2: RMSEs versus SNR: Cauchy noise, $8 \times 8 \times 20$, $F = 2$



Performance

- ☞ Still workhorse, after all these years ...
- ☞ convergence becomes extremely slow
- ☞ For difficult datasets, so-called swamps are possible: progress towards computational cost
- ☞ Main shortcoming of ALS and related algorithms is the high parameter estimates are still accurate
- ☞ identifiable conditions only, which means that at high SNR the close to the identifiable boundary; but ALS works under model
- ☞ Performance is worse (and further from the CRB) when operating data it is easy to get to the large-samples regime: e.g.,
- ☞ ALS works well in AWGN because it is ML-driven, and with 3-way

Performance

- 3-way workshop: TRICAP 2000: Fairborn, OH, USA; 2003, Kentucky, USA; 2006, Chania-Crete Greece.
- Hard-to-find original papers (Richard Harshman):
 - <http://publis.uwo.ca/~harshman/>
- 3-Mode Company (Peter Kroonenburg):
 - <http://www.ledenuniv.nl/fsw/three-mode/3mode.htm>
 - <http://www.modells.kvl.dk/courses/>
 - <http://www.modells.kvl.dk/users/rasmus/>
- 3-way group at KVL/DK (Rasmus Bro):
 - <http://www.ece.umn.edu/users/nikos/www.telecom.tuc.gr/~nikos>
 - <http://www.ece.umn.edu/users/nikos/www.telecom.tuc.gr/~nikos/and>
- Group homepage (Nikos Sidiropoulos):
 - <http://www.ece.umn.edu/users/nikos/www.telecom.tuc.gr/~nikos/and>

Learn more - tutorials, bibliography, papers, software, ...

- Major challenges: Unique models: i) Easy to check necessary & sufficient conditions; ii) Higher-way models; iii) Uniqueness under super-symmetric models (INDSCAL, JD, HOS)
 - Major challenges: Algorithms: Faster at small performance loss; incorporation of application-specific constraints
 - New exciting applications: Yours!
- Take home point: ($N < 3$)-way arrays are different; Low-rank models unique, have many applications

What lies ahead & wrap-up

☞ Thank you!



Preaching the Gospel of 3-Way Analysis